

Compositional Model Checking via Monoidal Categories



From (Abstract) Category Theory to (Concrete) Fast and Scalable Algorithms

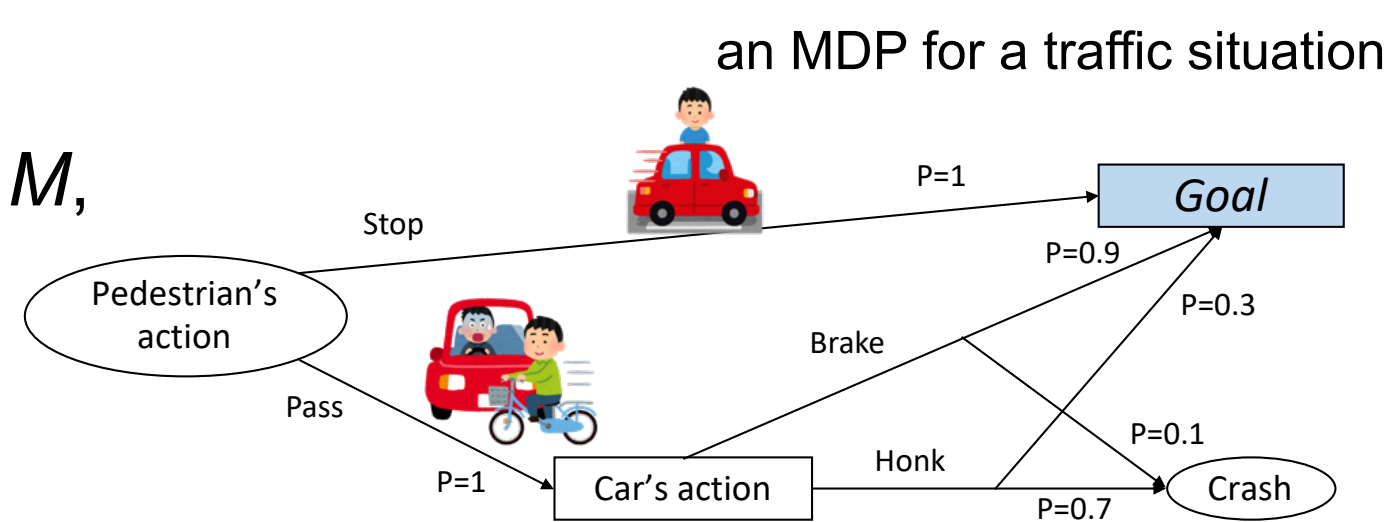
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Compositional Probabilistic Model Checking with String Diagrams of MDPs, Proc. CAV 2023. See also [Watanabe+, TACAS'24 & CAV'24]

Abstract. We present the first MDP model-checking algorithm that is fully compositional and automatic. It is a rare example of abstract category theory leading to concrete algorithmic merits.

Model Checking: Graph-Based Automated Analysis

We study the following problem
(**probabilistic model checking**):

- **given a Markov decision process (MDP) M ,**
- **compute its optimal expected reward.**
 - “expected”: an action leads to a randomized next state
 - “optimal”: for the best choice of actions (*strategy*)



An important problem, tackled also in reinforcement learning:

- finding the optimal strategy → **decision making**
- precise computation of exp. reward → **quality guarantee**

A topic heavily studied in the formal verification community (e.g. CAV).
Baier, C., Katoen, J.: Principles of model checking. MIT Press (2008)

Scalability is a challenge—sometimes an MDP has $\sim 10^8$ states (or more).
“State explosion.” **We want a scalable algorithm.**

Category Theory: an Abstract Language of Modern Math

Category theory is a language of modern mathematics

(Mac Lane, Eilenberg, Grothendieck, ...).

- It describes abstract structures using arrows,
- thus identifying essential similarities in different fields (e.g. algebra and geometry)

Use of category theory has been pursued in **computer science**, too

Functional programming and logic (Lawvere, Lambek, ..., cf. Haskell)
Coalgebra and process theory (Jacobs, Rutten, ...)

- “Get the setting right, then the problem solves itself”

However, the use of category theory has been mostly as a **theoretical backend**

- It helps to come up with a theory (definitions, correctness theorems)
- But **concrete algorithmic benefits have been rare**

Grothendieck's pursuit of simplicity and elegance: Nut opening example

Method 1 (Alexander Grothendieck, 1928-2014): Quicker to get to a solution. The solution is specific, not transportable. It does not scale.

Method 2: Takes time. The solution, once found, is generic, widely applicable (other kind of nuts, shellfish, ...), scalable (use a bigger pool).

→ Once we establish the **right environment** (~ **formulation, definition, language**), a problem solves by itself (as Grothendieck did)

Compositionality: Algebraic “Divide-and-Conquer” for Scalability

Compositionality is a paradigm eagerly pursued in computer science. It comes with performance advantage as well as mathematical blessing

The solution of a composition is obtained by ...

$$\mathcal{S}(\mathcal{A} \star \mathcal{B}) = \mathcal{S}(\mathcal{A}) \star \mathcal{S}(\mathcal{B})$$

Composition of **systems** (seqComp, parComp, sum, ...)

first solving the components \mathcal{A}, \mathcal{B} and then composing their solutions

Conceptual Value	Performance Advantage	Mathematical Blessing
<ul style="list-style-type: none"> • “Divide-and-Conquer”: simplifies a problem into smaller subproblems • $\mathcal{S}(\mathcal{A}), \mathcal{S}(\mathcal{B})$ are summaries of components \mathcal{A}, \mathcal{B}. Unnecessary details get abstracted away 	<ul style="list-style-type: none"> • Clear adv. when there are duplicates (reuse $\mathcal{S}(\mathcal{A})$!) $\mathcal{S}(\mathcal{A} \star \dots \star \mathcal{A}) = \mathcal{S}(\mathcal{A}) \star \dots \star \mathcal{S}(\mathcal{A})$ <ul style="list-style-type: none"> • (In some cases you don't need duplicates, e.g. mergesort) 	<ul style="list-style-type: none"> • Compositionality means that the solution $\mathcal{S}: \mathbb{M} \longrightarrow \mathbb{S}$ <p>is a homomorphism, preserving the operation \star</p>

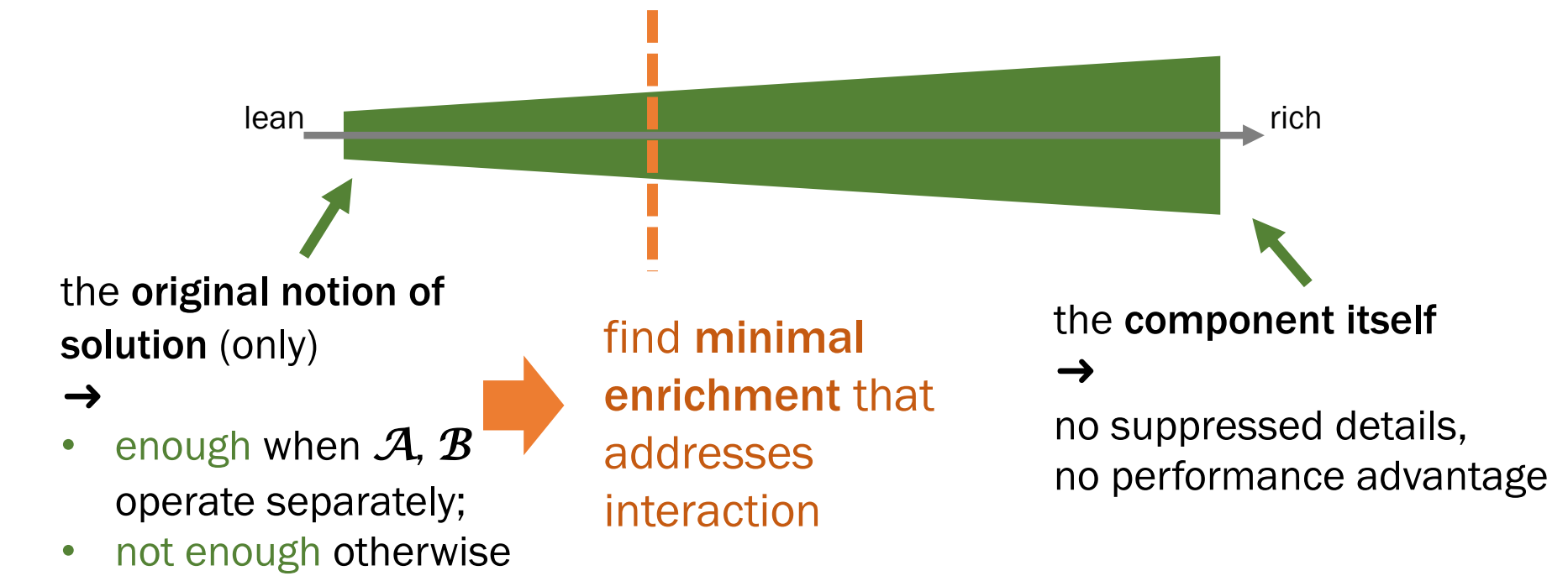
“Semantical Granularity” as a Challenge

Compositionality is not easy to achieve, though... one has to strike the right “**granularity of semantics**”

$$\mathcal{S}(\mathcal{A} \star \mathcal{B}) = \mathcal{S}(\mathcal{A}) \star \mathcal{S}(\mathcal{B})$$

Imagine: estimating the output of a team of two

Q. What information should the summaries $\mathcal{S}(\mathcal{A}), \mathcal{S}(\mathcal{B})$ carry?



Monoidal Categories Come to the Rescue

We use **string diagrams** for composing MDPs. They come from monoidal categories

String Diagram of MDPs	Background: Monoidal Categories
<ul style="list-style-type: none"> • Sequential composition ; • Sum \oplus • and some “constants” $\langle \cdot \rangle, \cdot, \otimes, \dots$ → planar composition of MDPs (mostly <i>sequential</i> composition; not parallel) • Loop is a derived operation: 	<ul style="list-style-type: none"> • Well-established field of category theory (Mac Lane, Kelly, Joyal, Street, ...) • Used for many applications: quantum field theory (Khovanov, ...), quant. computation (Abramsky, Coecke, Vicary, Heunen, ...), linguistics (Sadzadeh, Coecke, ...), signal flow diagrams (Bonchi, Sobocinski, Zanasi, ...), ... • String diagrams as an <i>internal language</i> for monoidal categories (Joyal & Street, Adv. Math. 1991) <ul style="list-style-type: none"> • nicely expressive (planar composition, see left) • comes with a rich metatheory (see later) • In particular, we use string diagrams for compact closed categories (compCCs). <ul style="list-style-type: none"> • Dual object A^* for each A • Example: fin.-dim. vector spaces, MDPs, ...

Use of monoidal categories comes with two notable benefits.

Benefit 1: Settling “Granularity of Semantics”	Benefit 2: Framework Upgrades for Free (uni-dir. MC → uni-dir. MDP → bi-dir. MDP)
<ul style="list-style-type: none"> • Compositional solution is a homomorphism $\mathcal{S}: \mathbb{M} \longrightarrow \mathbb{S}$ • The domain \mathbb{M} is a compact closed category (compCC) of MDPs → We need \mathbb{S} to be a compCC too! <ul style="list-style-type: none"> • Minimally enrich the original solution domain (optimal expected reward) till it becomes a compCC • Turns out: it suffices to additionally compute reachability probabilities <ul style="list-style-type: none"> • “decomposition equalities” (right) 	<ul style="list-style-type: none"> • Reachability probabilities decompose into themselves: $\mathbf{RPr} \left\{ \left\langle \begin{array}{c} \downarrow \\ \text{ } \end{array} \right\rangle \right\} = \sum_k \mathbf{RPr} \left\{ \left\langle \begin{array}{c} \downarrow \\ \text{ } \end{array} \right\rangle \right\} \times \mathbf{RPr} \left\{ \left\langle \begin{array}{c} \downarrow \\ \text{ } \end{array} \right\rangle \right\}$ • Similar decomposition of expected rewards requires more data: $\mathbf{ERw} \left\{ \left\langle \begin{array}{c} \downarrow \\ \text{ } \end{array} \right\rangle \right\} = \sum_k \mathbf{RPr} \left\{ \left\langle \begin{array}{c} \downarrow \\ \text{ } \end{array} \right\rangle \right\} \times \mathbf{ERw} \left\{ \left\langle \begin{array}{c} \downarrow \\ \text{ } \end{array} \right\rangle \right\} + \sum_k \mathbf{ERw} \left\{ \left\langle \begin{array}{c} \downarrow \\ \text{ } \end{array} \right\rangle \right\} \times \mathbf{RPr} \left\{ \left\langle \begin{array}{c} \downarrow \\ \text{ } \end{array} \right\rangle \right\}$ • The same for loops $\left[\begin{array}{c} \downarrow \\ \text{ } \end{array} \right] = \left[\begin{array}{c} \downarrow \\ \text{ } \end{array} \right] \cdot \sum_k \left[\begin{array}{c} \downarrow \\ \text{ } \end{array} \right]$ • (NB: no actions so far, this is about Markov chains → next slide)
<p>Building semantical frameworks is easy in a simple setting (<i>rightward-open MCs</i>; no action, end points are all rightward)</p> <p>Upgrades are for free, exploiting the categorical metatheory change of base (Eilenberg, Kelly, ...), the Int construction (Joyal, Street, Verity)</p>	<p>Diagram showing the upgrade from unidirectional MDPs to bidirectional MDPs using the Int construction.</p>

Algorithmic Outcomes

- The first MDP model checking algorithm that is fully compositional and automatic inspired by [Junges+, CAV'22] (not fully compositional), [Kwiatkowska+, Inf. Comp. '13] (not fully automatic)
- Can be **arbitrarily faster** than non-compositional algorithms (increase duplicates!); we observed max. x 6000 speed-up
- Many large systems are built compositionally → practical potential

exec. time [s]					exec. time [s]						
benchmark	Q	E	DI-high	DI-mid	DI-low	benchmark	Q	E	FZ-none	FZ-int.	FZ-all (PRISM)
Patrol1	10^6	10^6	21	42	83	Packets1	$2.5 \cdot 10^5$	$5 \cdot 10^5$	TO	1	65
Patrol2	10^6	10^6	23	48	90	Packets2	$2.5 \cdot 10^5$	$5 \cdot 10^5$	TO	3	64
Patrol3	10^6	10^6	22	43	89	Packets3	$2.5 \cdot 10^5$	$5 \cdot 10^5$	TO	1	56
Patrol4	10^6	10^6	39	69	121	Packets4	$2.5 \cdot 10^5$	$5 \cdot 10^5$	TO	3	56
Wholesale1	10^6	$2 \cdot 10^6$	130	260	394	Patrol5	10^6	10^6	22	22	TO
Wholesale2	10^6	$2 \cdot 10^6$	92	179	274	Wholesale5	$5 \cdot 10^5$	10^6	TO	14	TO
Wholesale3	$2 \cdot 10^6$	$4 \cdot 10^6$	6	12	23						
Wholesale4	$2 \cdot 10^6$	$4 \cdot 10^6$	129	260	393						

$|Q|$ is the number of positions; $|E|$ is the number of transitions (only counting action branching, not probabilistic branching); execution time is the average of five runs, in sec.; timeout (TO) is 1200

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