



Multimedia Information Retrieval



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MMIS
Multimedia and Information Systems



Why content-based?

Actually, what is content-based search?

Is human thinking content-based?

Metadata annotation (text) is good but

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-
-
-



1. What are multimedia queries?
2. Fingerprinting
3. Metadata & piggy-back retrieval
4. Automated image annotation
- 5 Visual content-based retrieval I (challenges + features)
- 6 Visual content-based retrieval II (distances)
7. Evaluation
8. Browsing, search and geography



Where are the challenges?

Image content analysis (diversity, semantic gap, polysemy)

Mapping to higher level (semantic representation)

Time taken and resources needed (“scalability”)

Automation, scale and coping with errors



The semantic gap



1m pixels with a spatial
colour distribution

faces & vase-like object

victory, triumph, ...

disappointment, ..



Polysemy

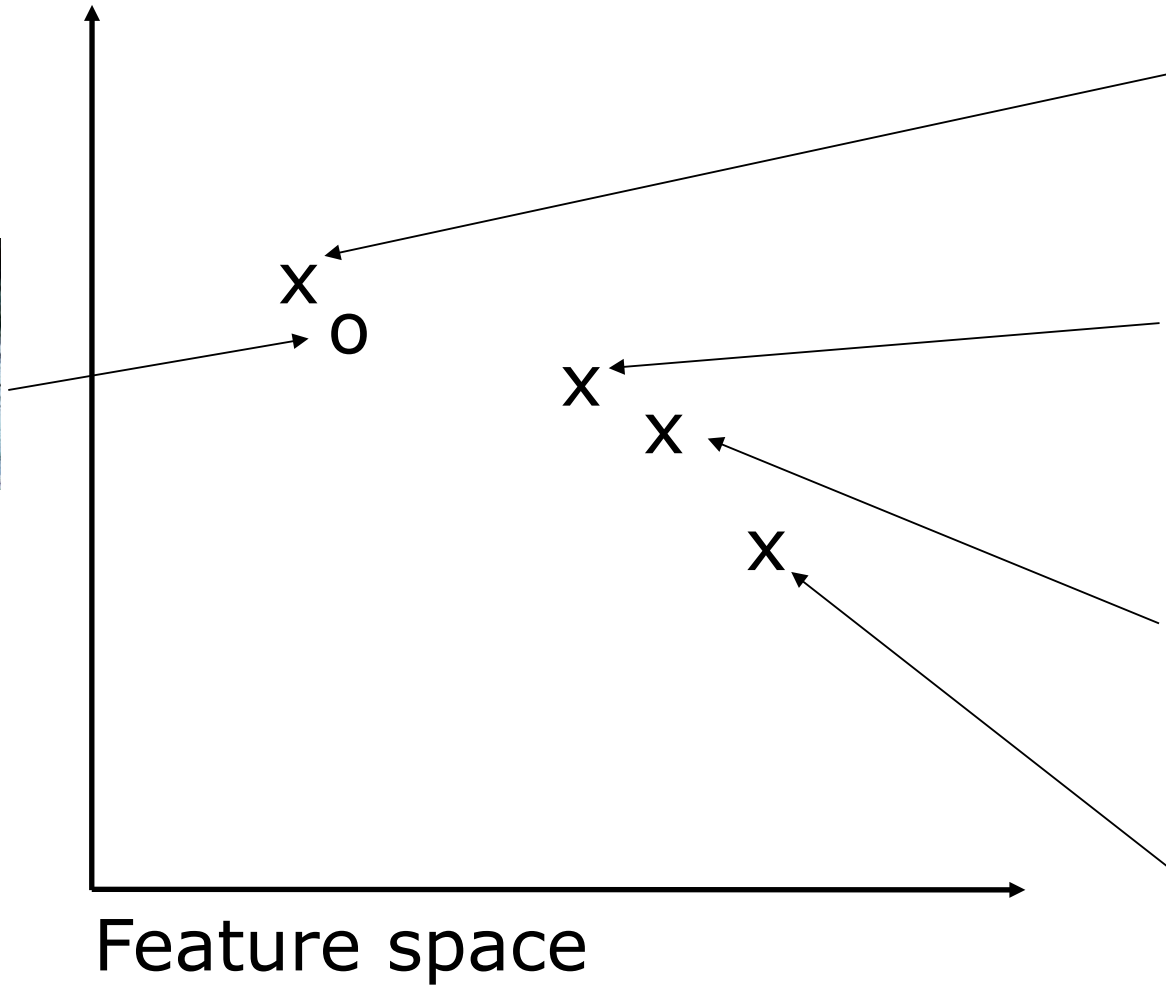


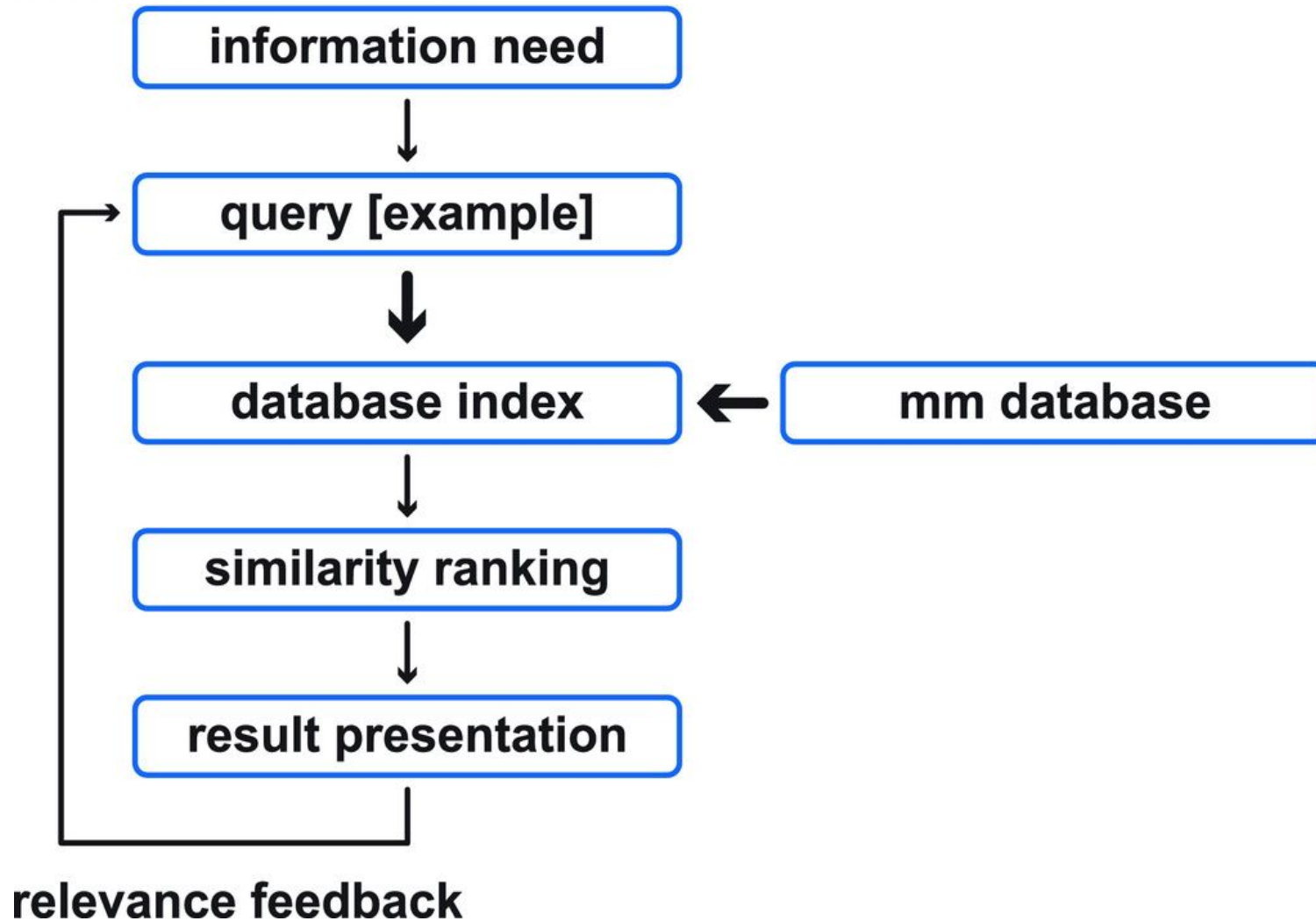


Scalability



Features and distances







Visual

Colour, texture, shape, edge detection, SIFT/SURF

Audio

Temporal

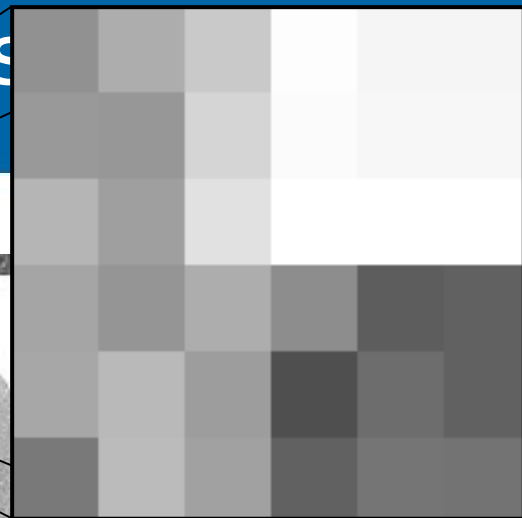
How to describe the features?

For people

For computers



Digital Images





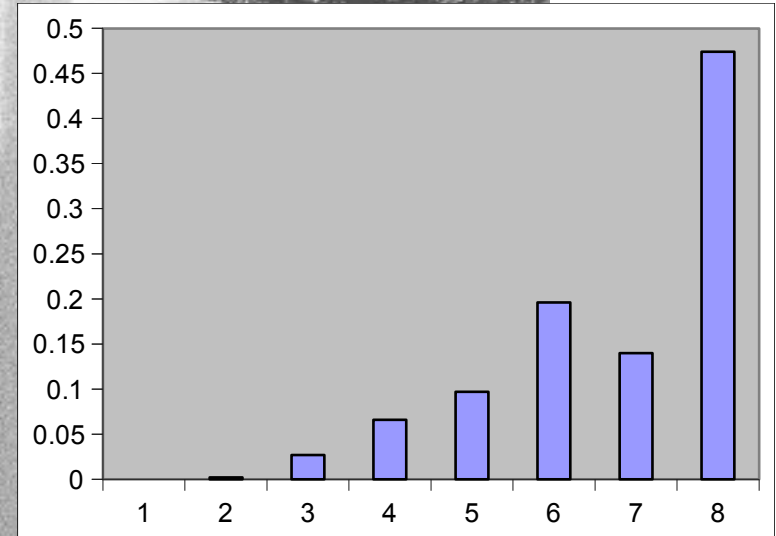
Content of an image



145	173	201	253	245	245
153	151	213	251	247	247
181	159	225	255	255	255
165	149	173	141	93	97
167	185	157	79	109	97
121	187	161	97	117	115



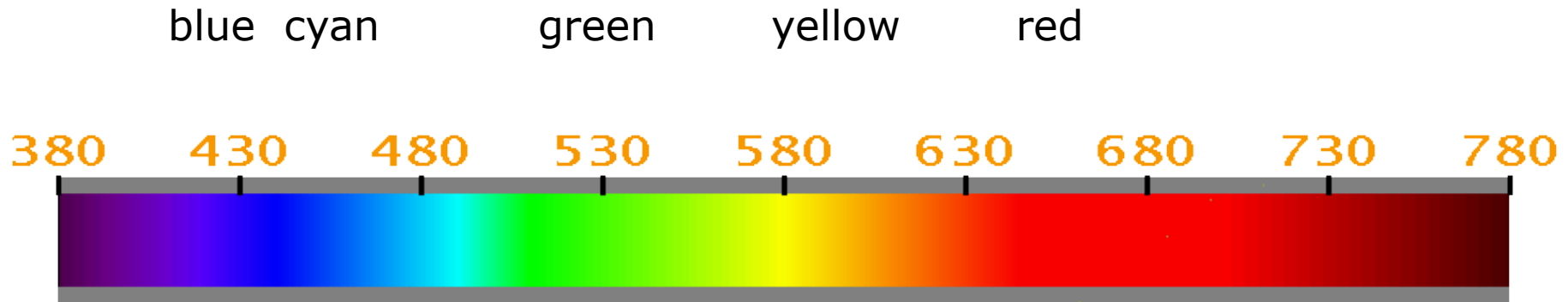
Histogram



1:	0	-	31
2:	32	-	63
3:	64	-	95
4:	96	-	127
5:	128	-	159
6:	160	-	191
7:	192	-	223
8:	224	-	255



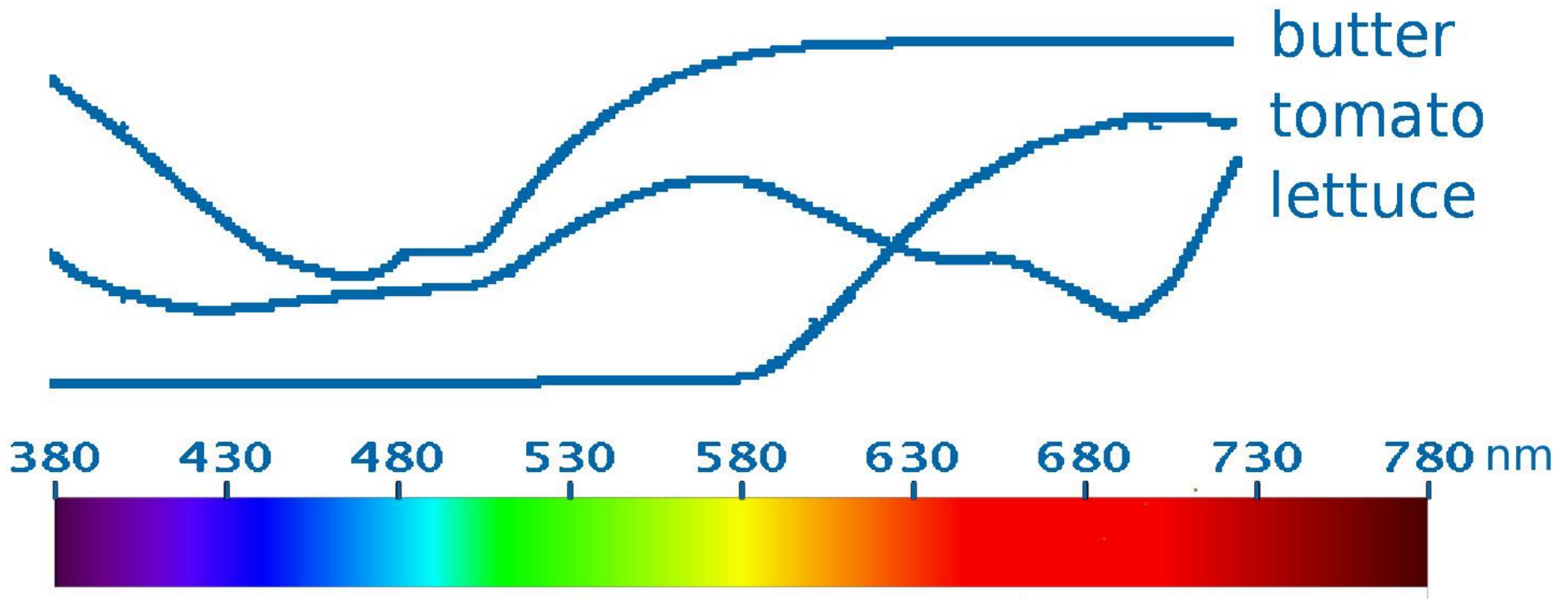
phenomenon of human perception
three-dimensional (RGB/CMY/HSB)
spectral colour: pure light of one wavelength

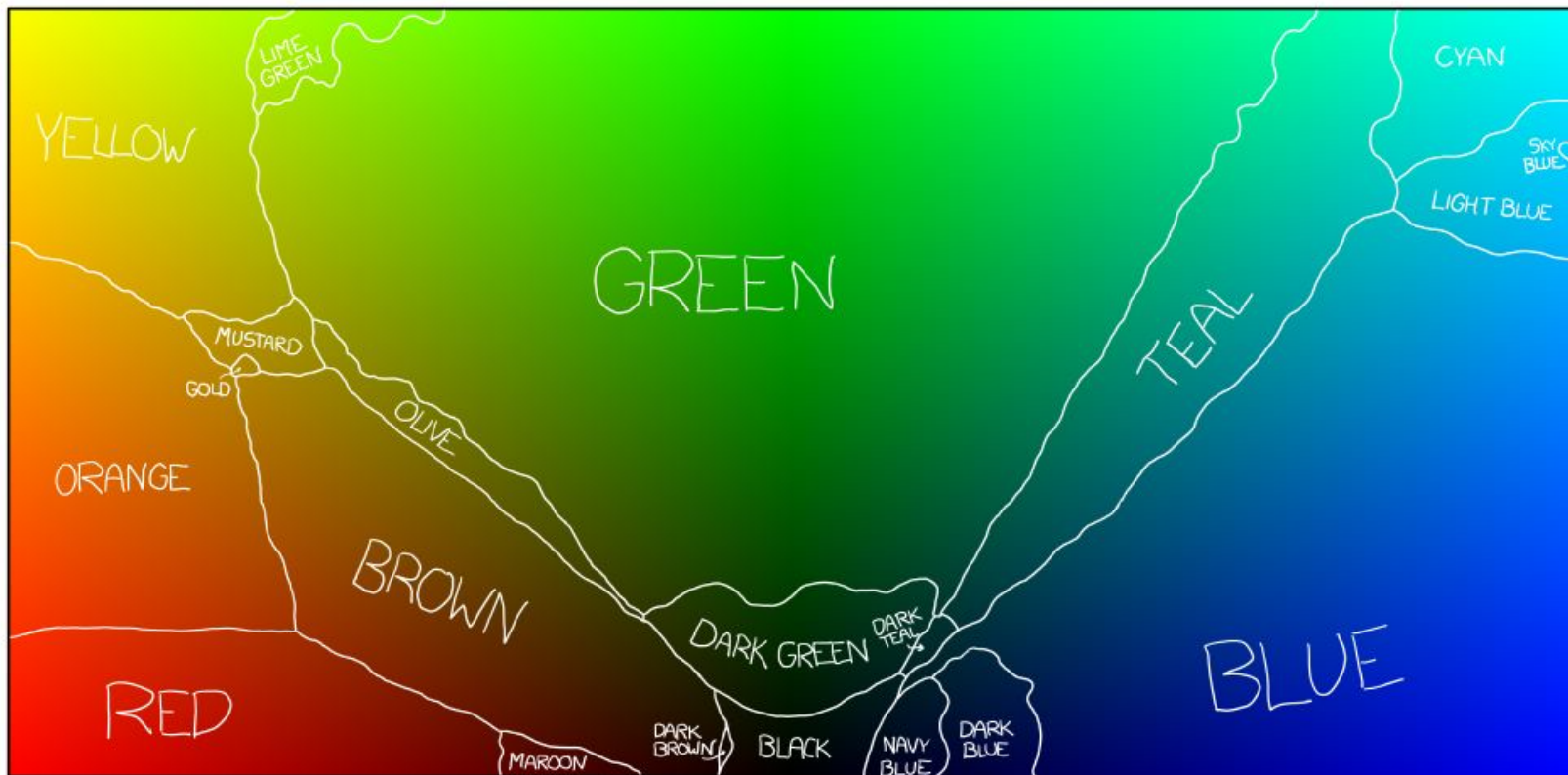


spectral colours: wavelength (nm)



Colour



















THIS CHART SHOWS THE DOMINANT COLOR NAMES OVER THE THREE FULLY-SATURATED FACES OF THE RGB CUBE (COLORS WHERE ONE OF THE RGB VALUES IS ZERO)





Colour: subjective

Color names if
you're a girl...

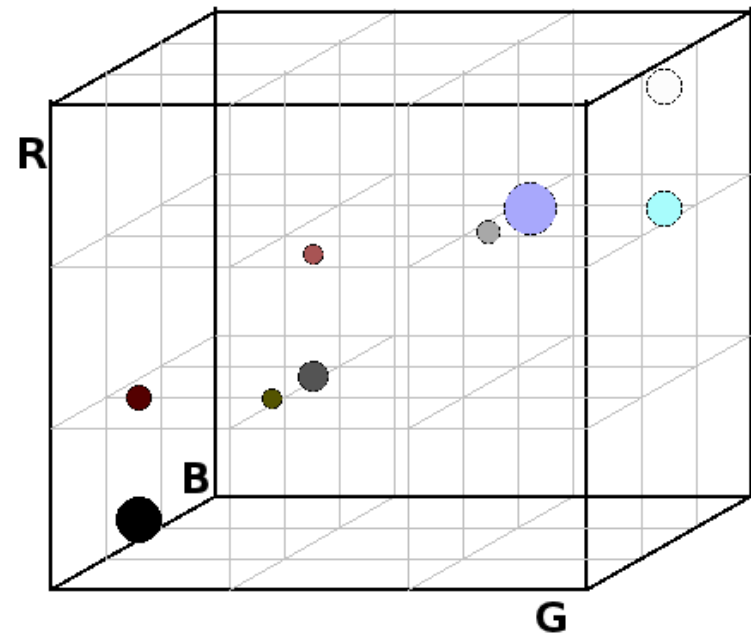
Maraschino		Red
Cayenne		
Maroon		Purple
Plum		
Eggplant		
Grape		
Orchid		Pink
Lavender		
Carnation		
Strawberry		
Bubblegum		
Magenta		Orange
Salmon		
Tangerine		

Color names if
you're a guy...

<http://eagereyes.org/blog/2011/you-only-see-colors-you-can-name>











Colour histogram





a) Sketch a 3D colour histogram for



R	G	B		
0	0	0		black
255	0	0		red
0	255	0		green
0	0	255		blue
0	255	255		cyan
255	0	255		magenta
255	255	0		yellow
255	255	255		white

b) Sketch 2D colour histograms per channel

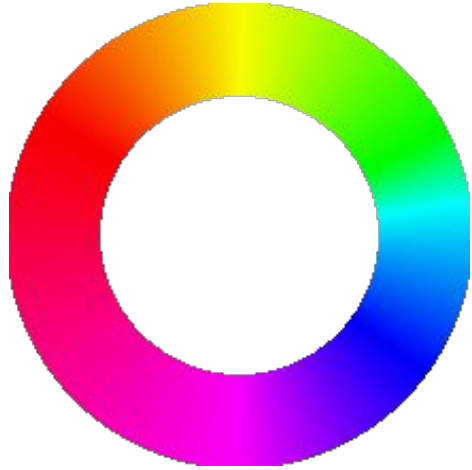
c) Which one is more informative? Why?



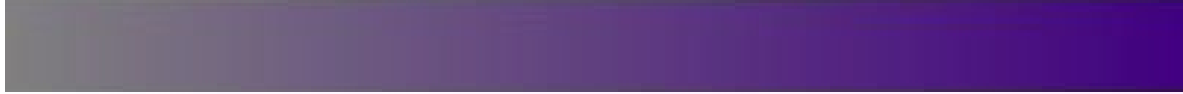
HSV, HSL, CIELAB/CIELUV




HSB colour model



hue (0° - 360°)
spectral colour



saturation (0% - 100%)
= spectral purity

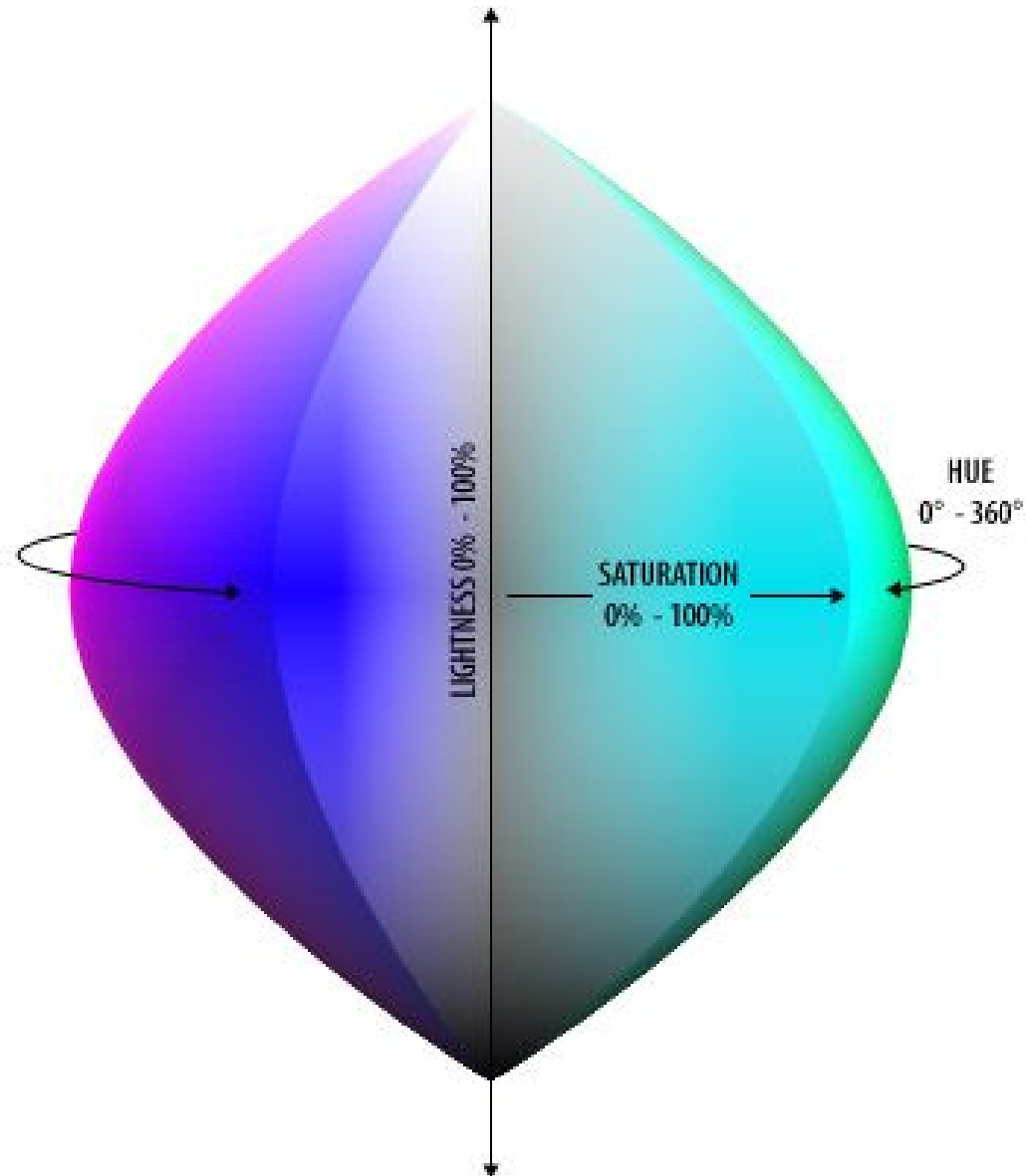


brightness (0% - 100%)
= energy or luminance

chromaticity = hue+saturation



HSB colour model





disadvantage: hue coordinate is not continuous

0 and 360 degrees have the same meaning

but there is a huge difference in terms of numeric distance

example:

red = (0,100%,50%) = (360,100%,50%)

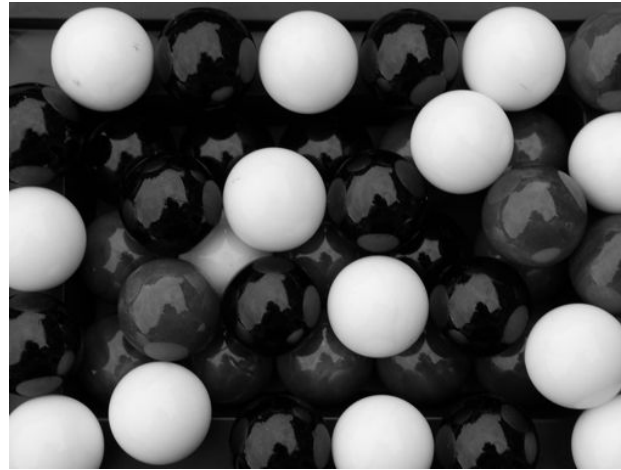
advantage: it is more natural to describe colour changes "brighter blue", "purer magenta", etc



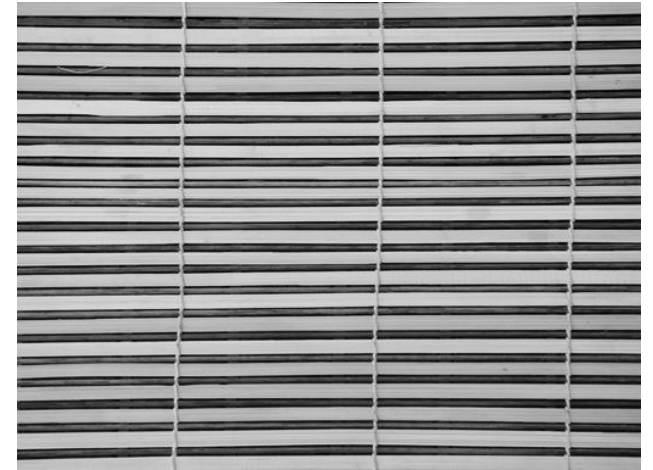
Texture



coarseness



contrast

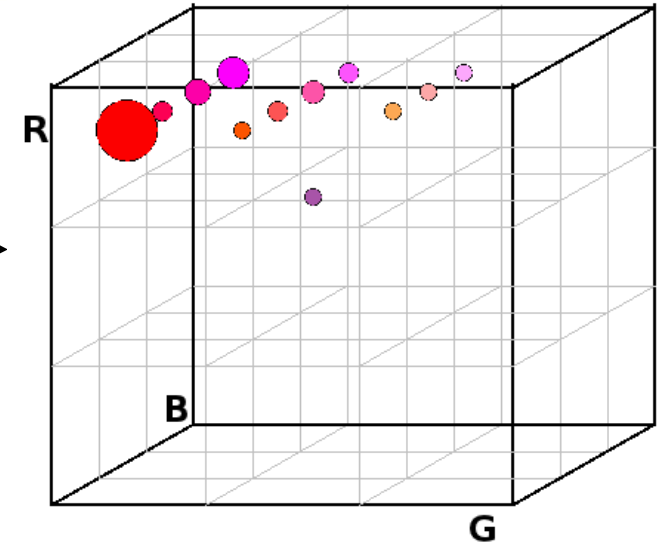
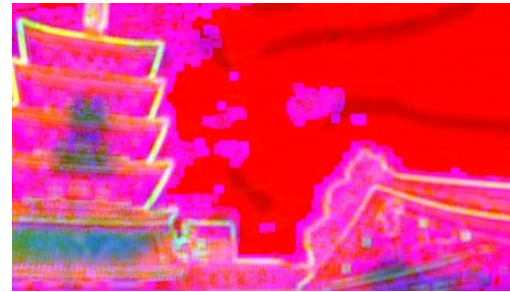


directionality

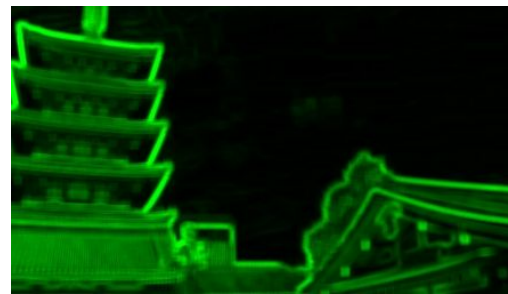
[Tamura et al, 1978]



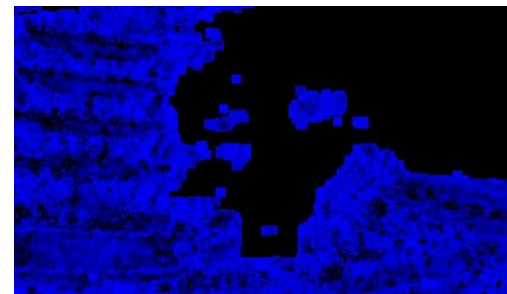
Texture histograms



Coarseness



coNtrast



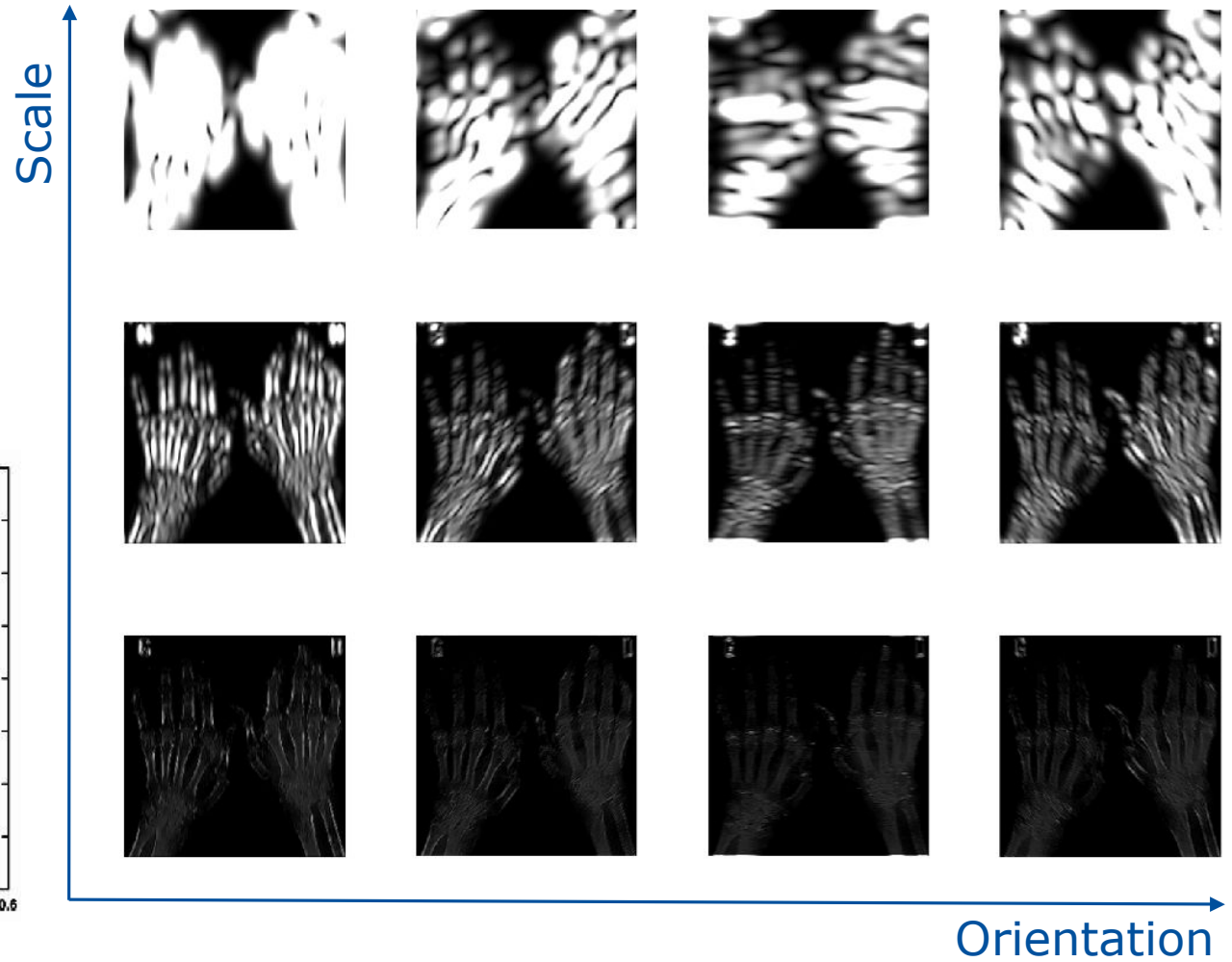
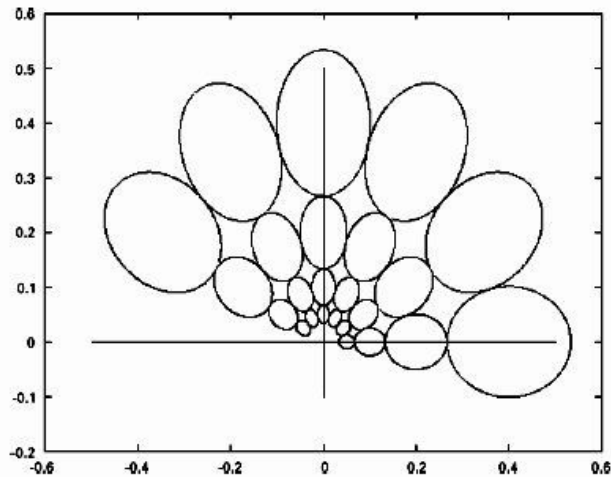
Directionality

[with Howarth, *IEE Vision, Image & Signal Proc* 15(6) 2004; Howarth PhD thesis]



Gabor filter

Query



[with Howarth, CLEF 2004]



shape = class of geometric objects invariant under
translation

scale (changes keeping the aspect ratio)

rotations

information preserving description
(for compression)

non-information preserving (for retrieval)

boundary based (ignore interior)

region based (boundary+interior)

Particularly important for drawings, eg, patent drawings



Reserach corpus of 19m **patents**: XML docs + tif images

CLEF-IP track 2011

- Image-based prior art search
- Image classification



212,867 patents (34k EP; 167k US; 12k WO)
2,586,767 tifs as attachments (min 1 per patent)

A43B characteristic features of footwear;
parts of footwear

A61B diagnosis; surgery; identification

H01L semiconductor devices;
electric solid state devices not otherwise provided for

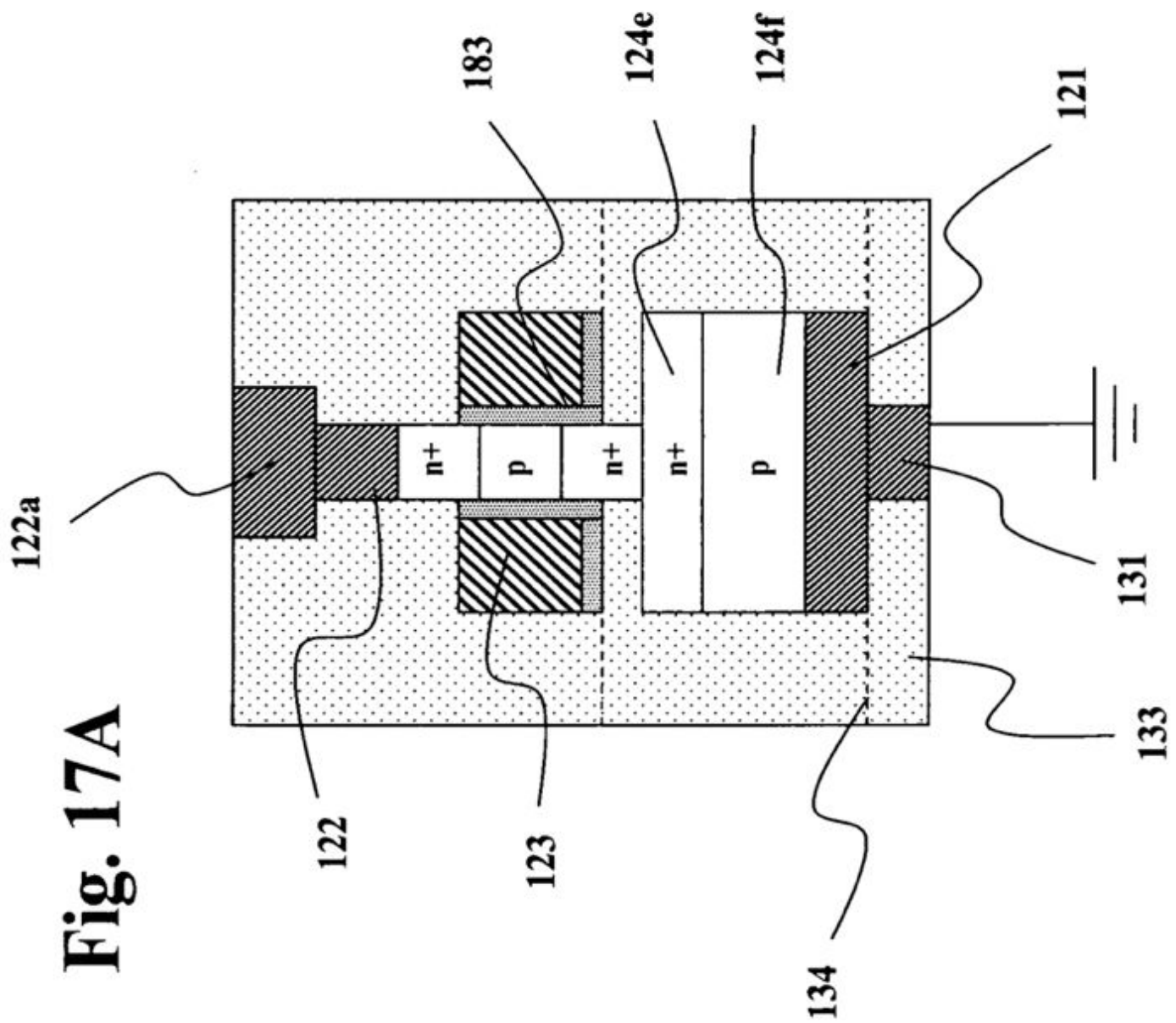


Fig. 17A

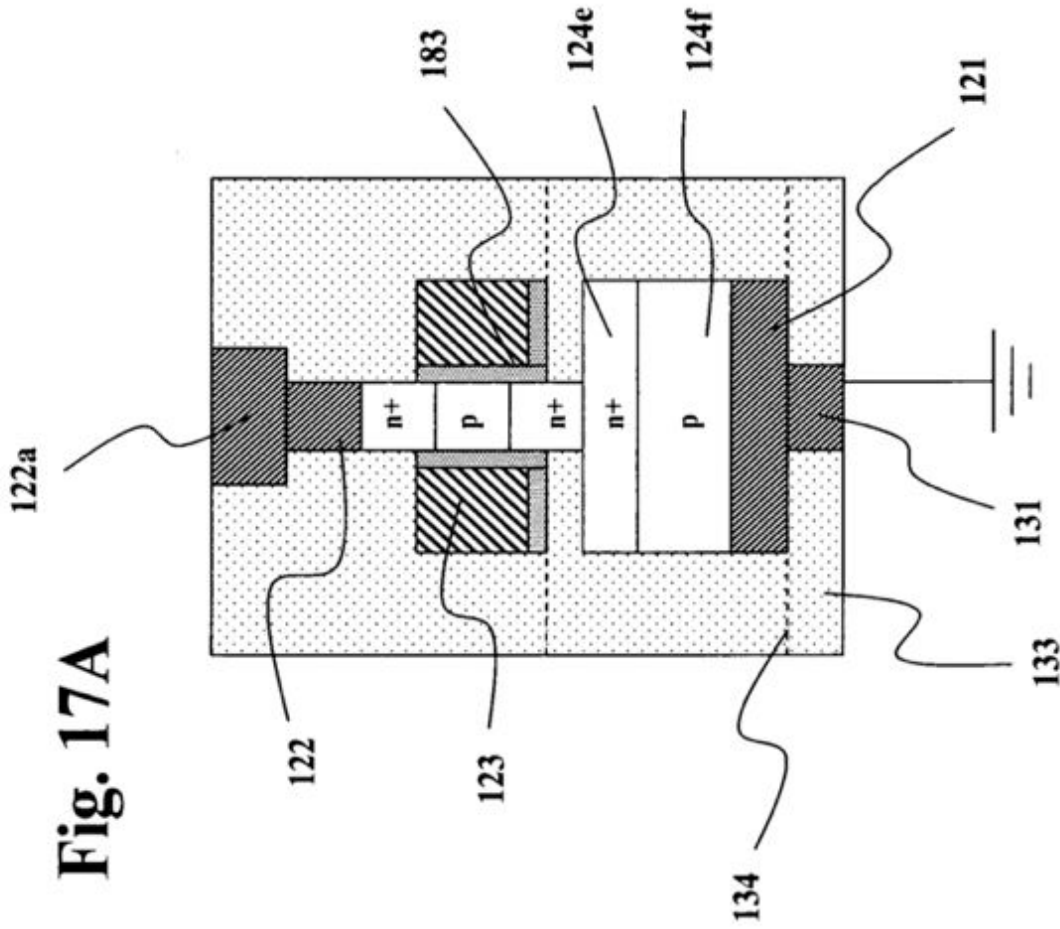
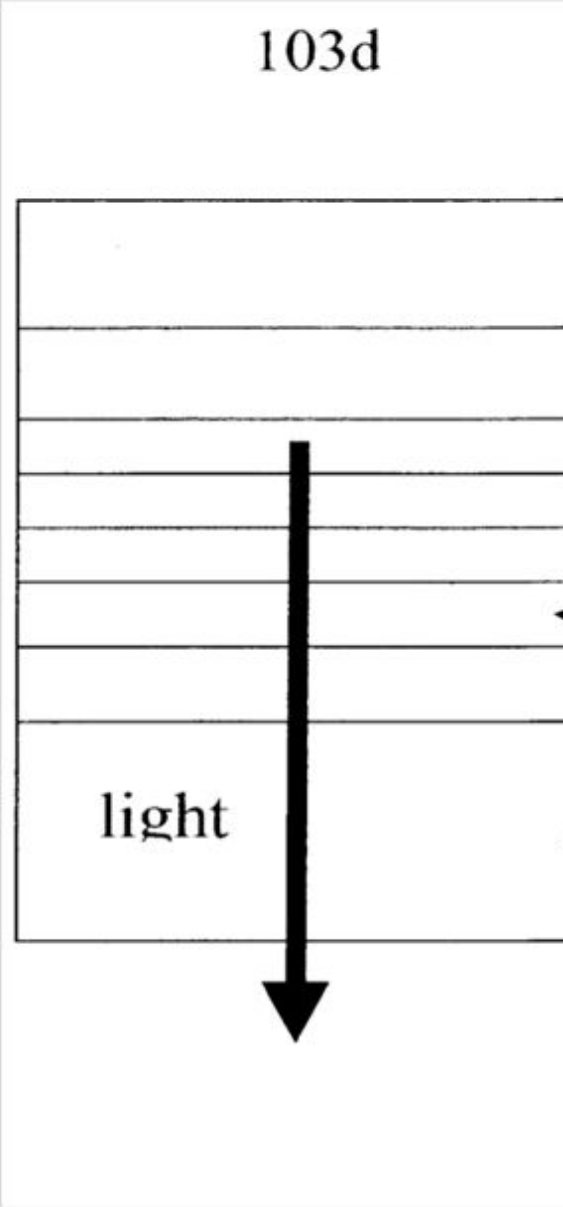
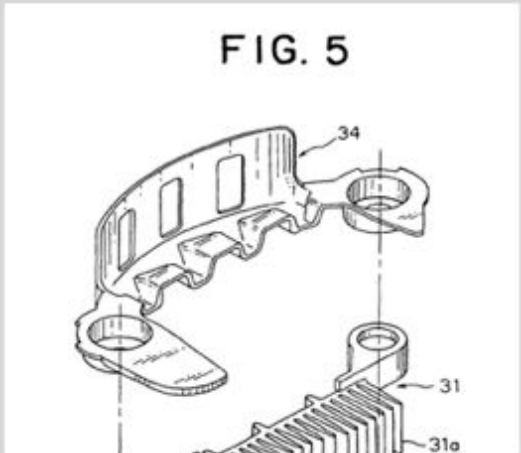
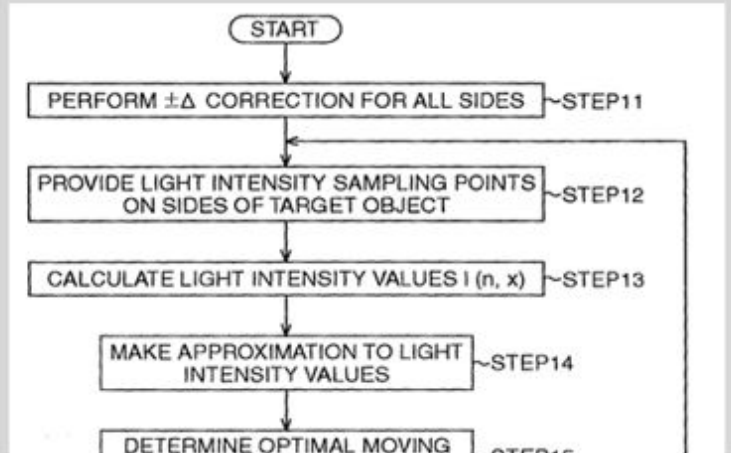
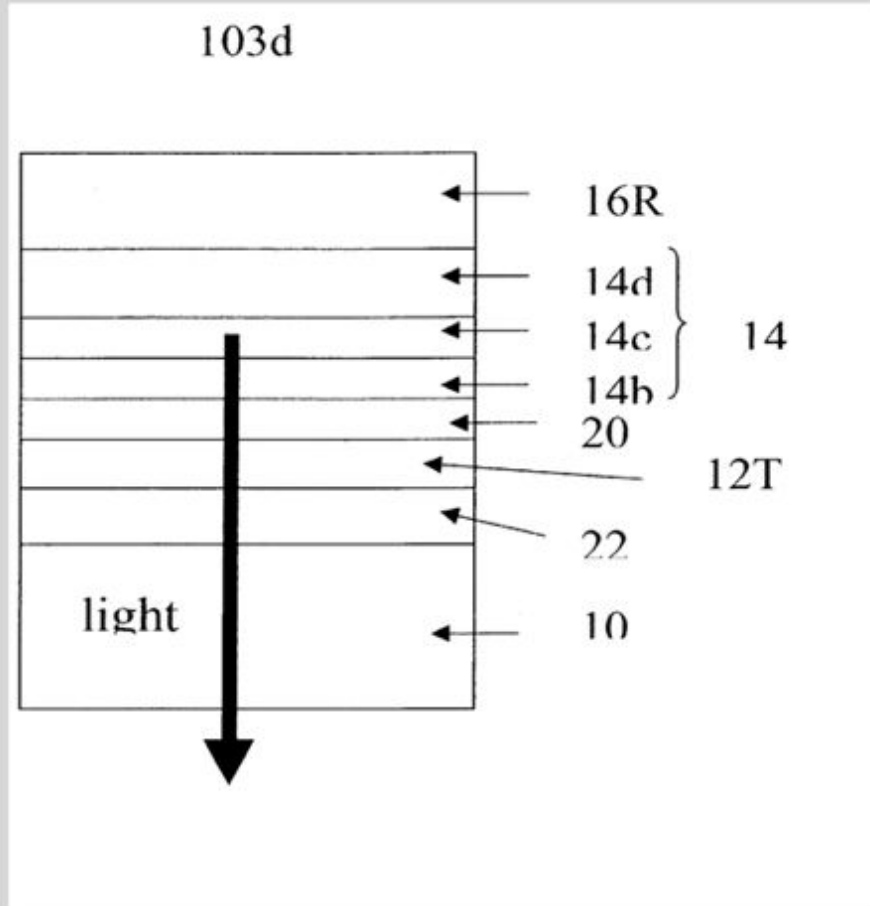
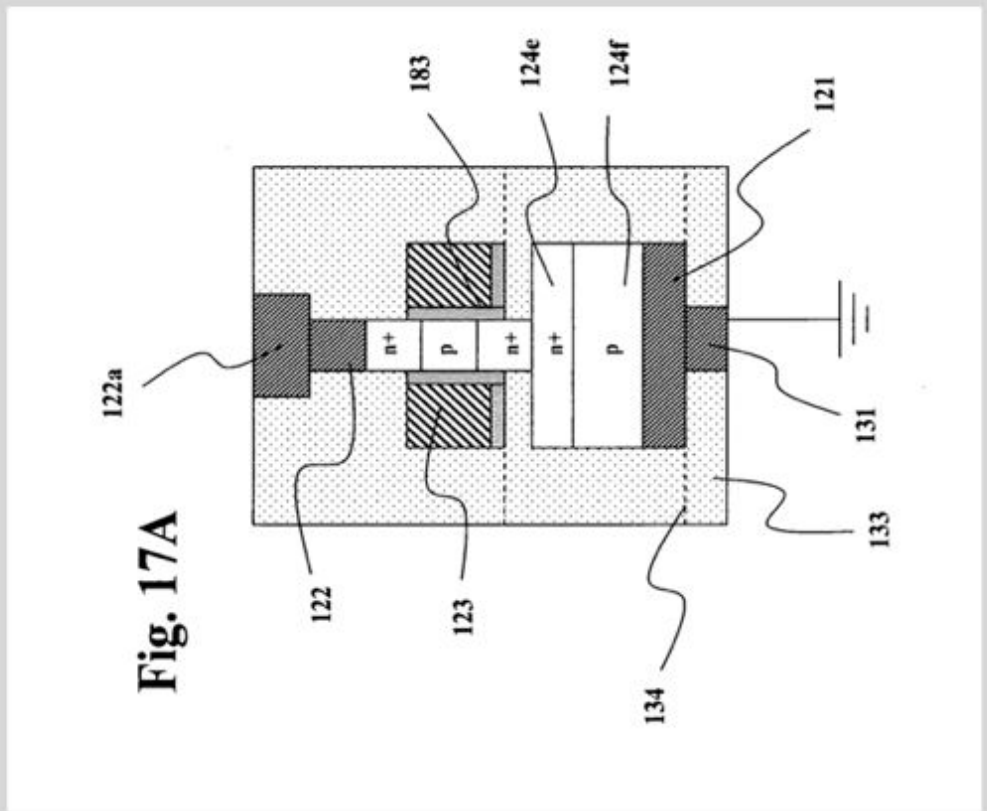


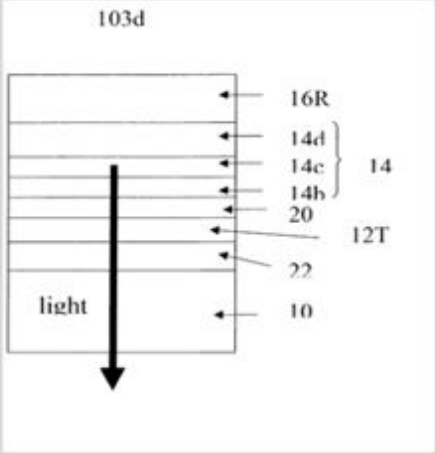
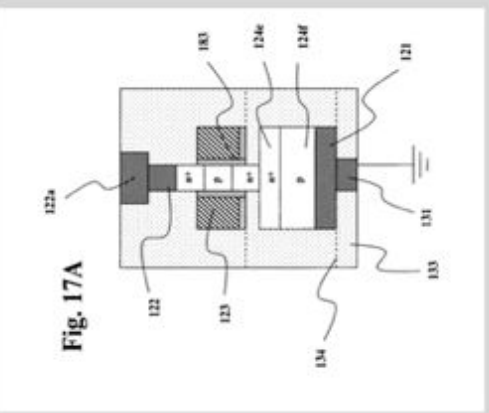
Fig. 17A



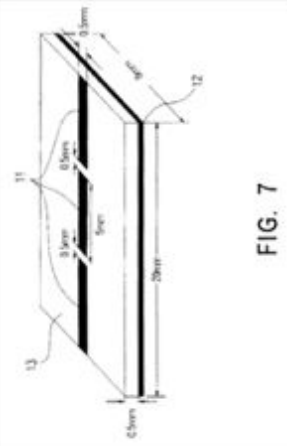
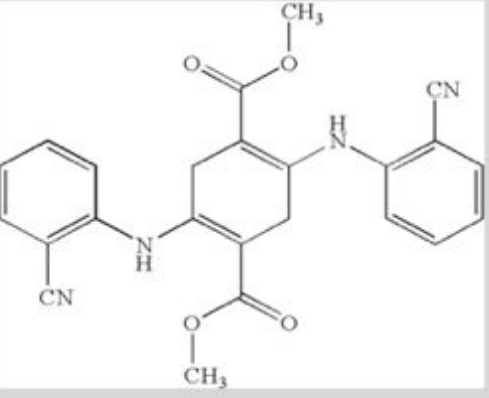
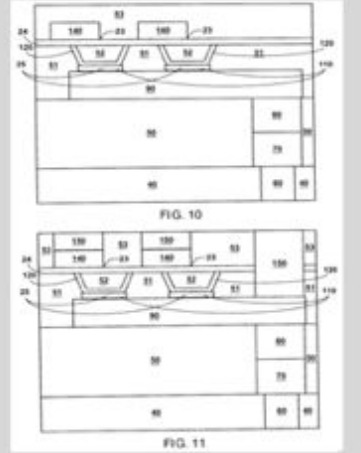
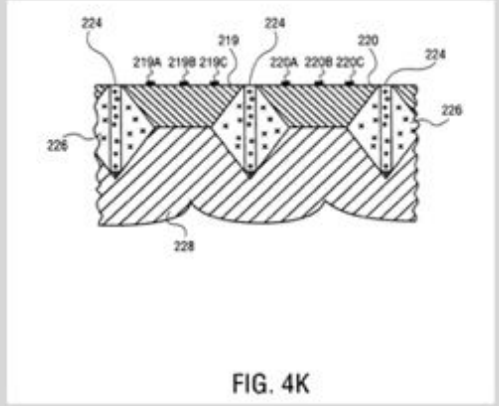
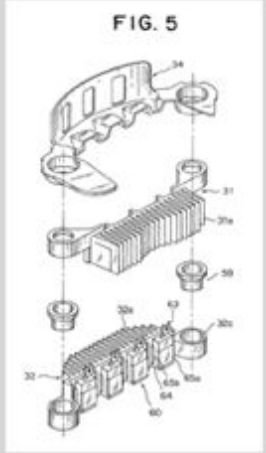
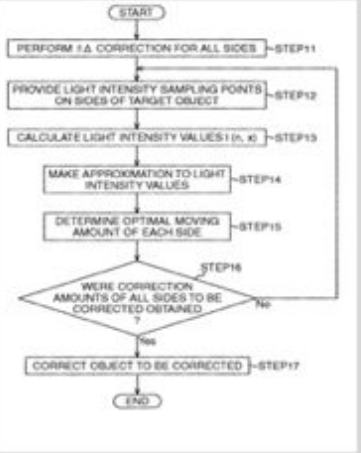
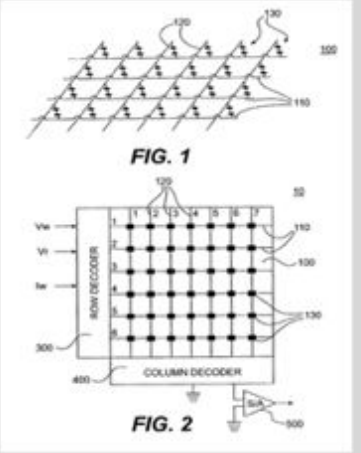
F



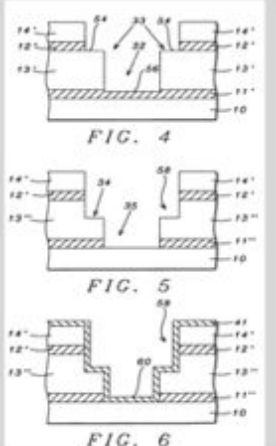
Randomly picked images (zooming out)



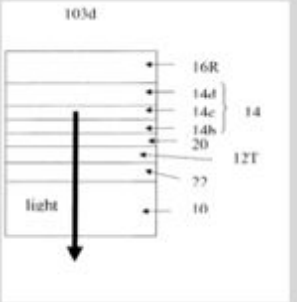
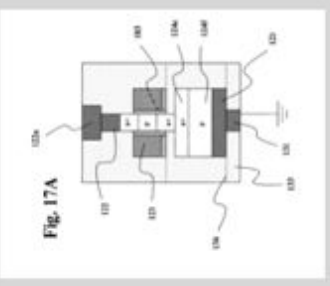
$$f[n] = \begin{cases} f[n], & n-1 < n < n+1 \\ 0, & \text{otherwise} \end{cases}$$



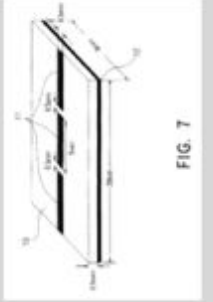
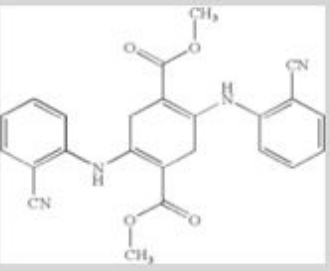
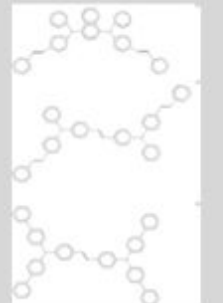
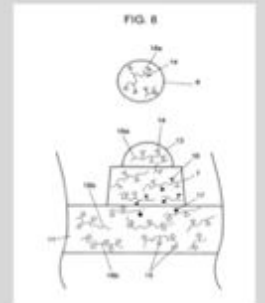
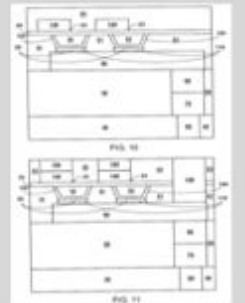
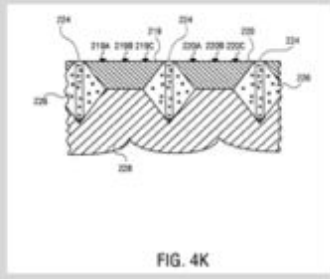
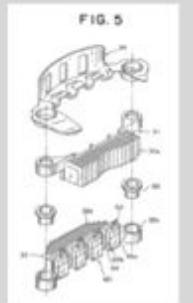
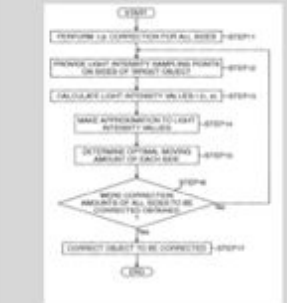
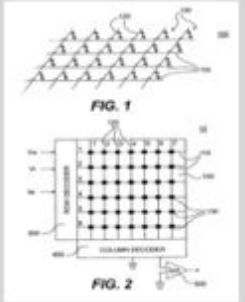
$$D_c \approx \frac{4\mu_r}{\mu_0 M_s^2} \left(\frac{2kT_c |K|}{a} \right)^{1/2}$$



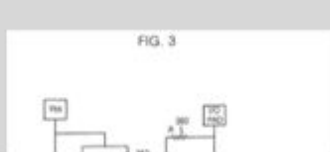
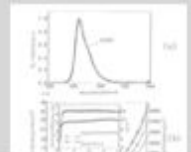
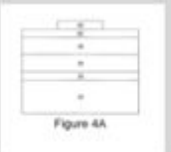
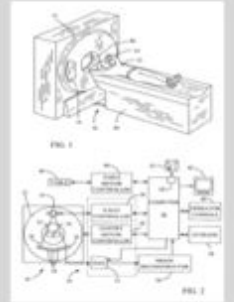
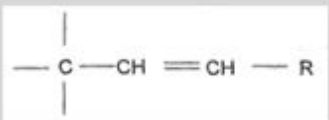
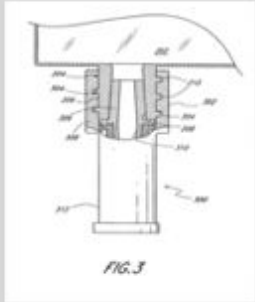
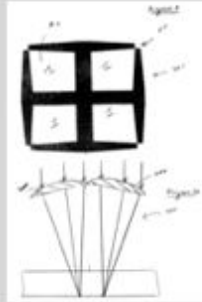
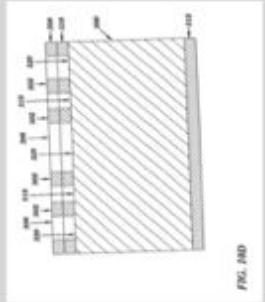
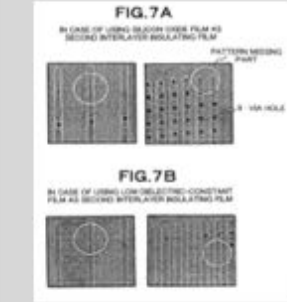
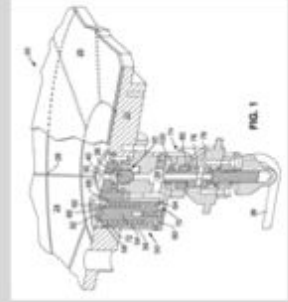
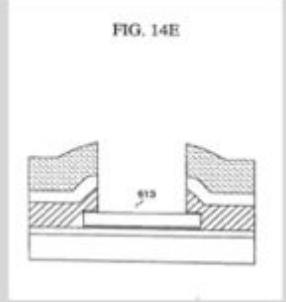
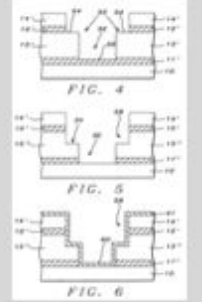
Randomly picked images (zooming out)



$$D_c \approx \frac{4\mu_r}{\mu_0 M_s^2} \left(\frac{2kT_c |K|}{a} \right)^{1/2}$$



$$D_c \approx \frac{4\mu_r}{\mu_0 M_s^2} \left(\frac{2kT_c |K|}{a} \right)^{1/2}$$



Randomly picked images (zooming out)

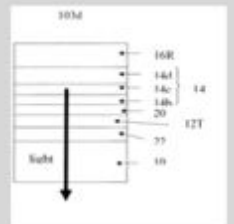
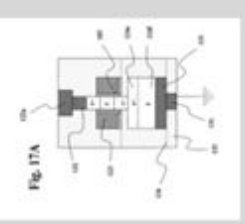
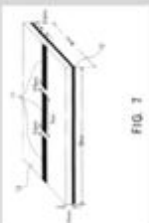
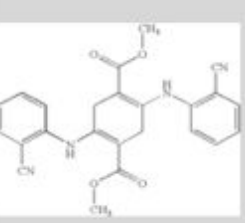
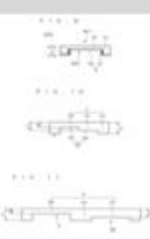
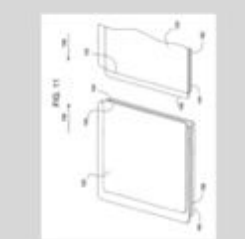
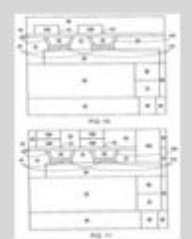
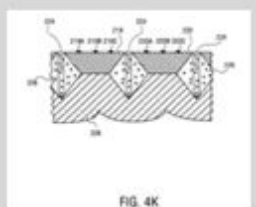
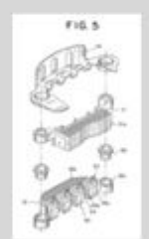
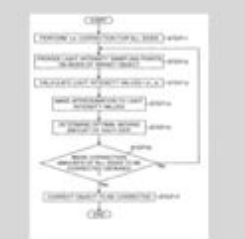
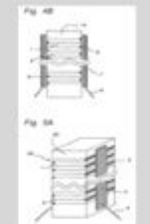
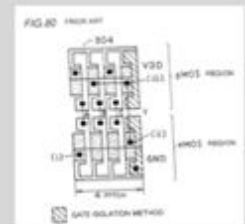
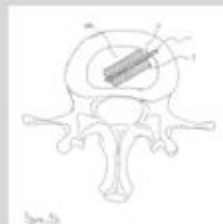
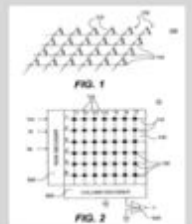


FIG. 17B



$$D_e \approx \frac{4\mu_e}{\mu_0 M_i^2} \left(\frac{2kT_e |K|}{a} \right)^{1/2}$$

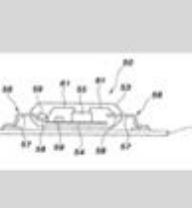
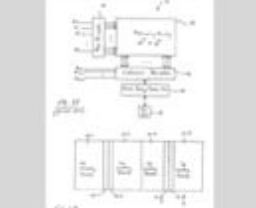
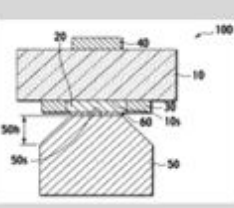
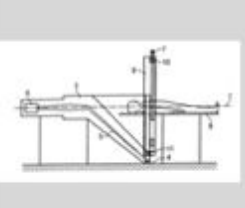
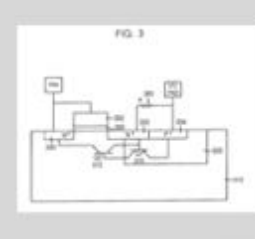
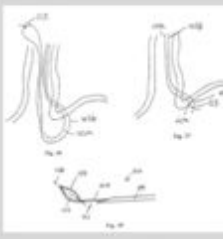
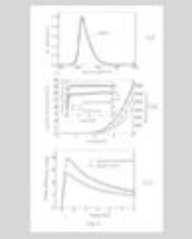
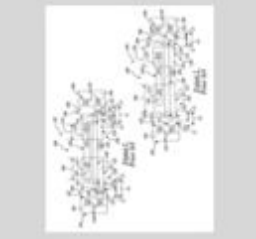
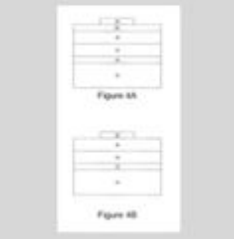
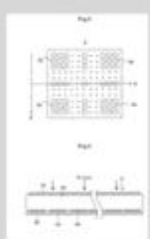
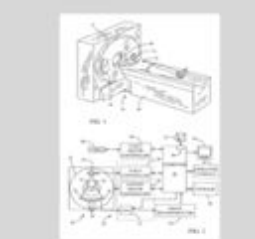
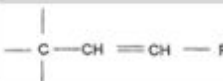
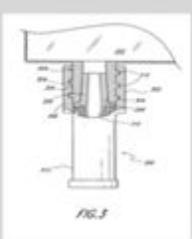
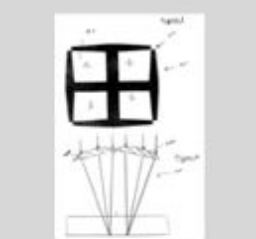
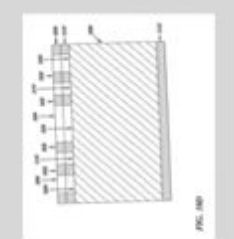
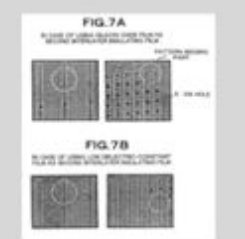
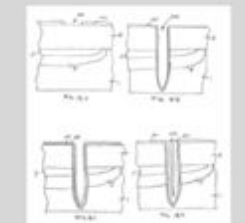
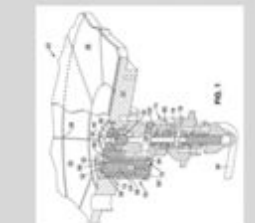
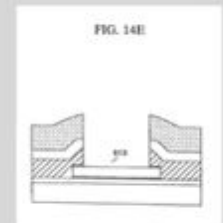
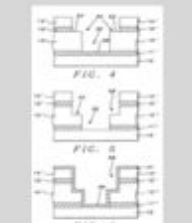
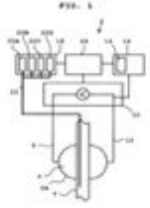
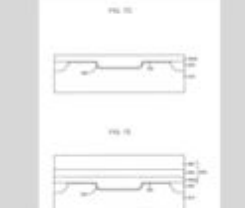
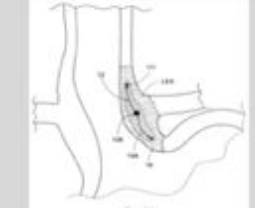
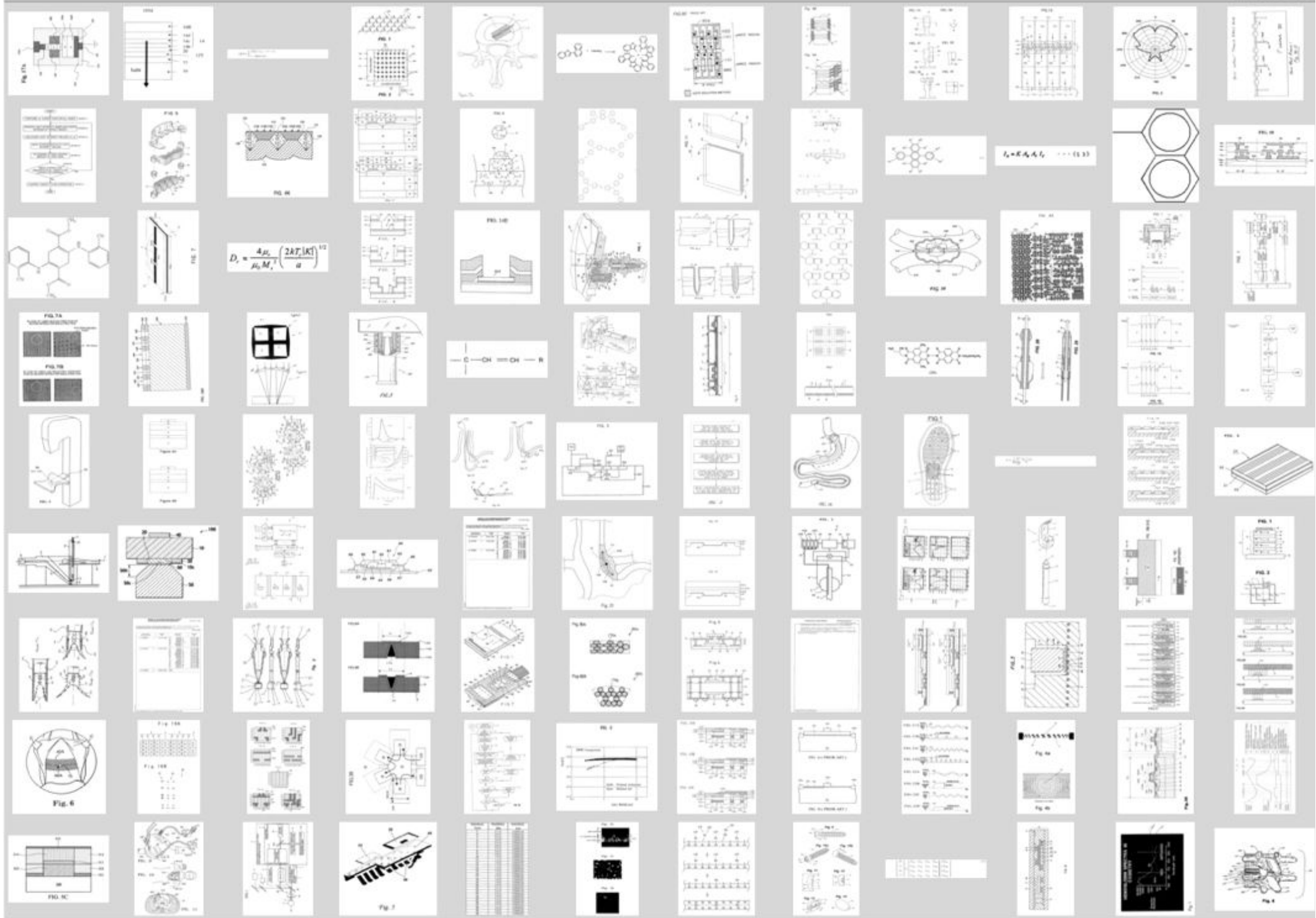


TABLE I	
Device	Parameter
Device 1	Value 1
Device 2	Value 2
Device 3	Value 3
Device 4	Value 4
Device 5	Value 5



Randomly picked 108 images



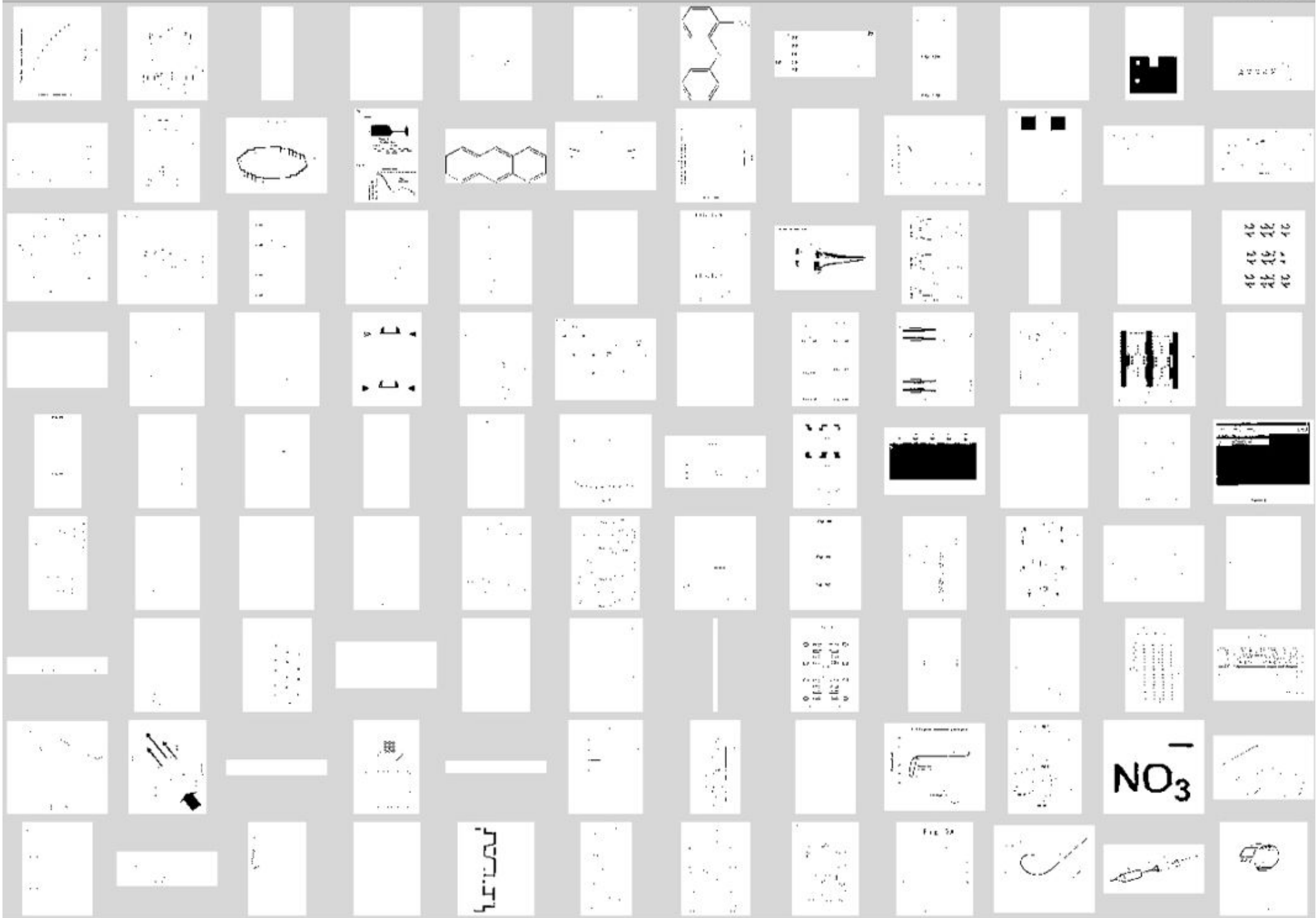
Randomly picked images (another set of 108)

random-c-16-a

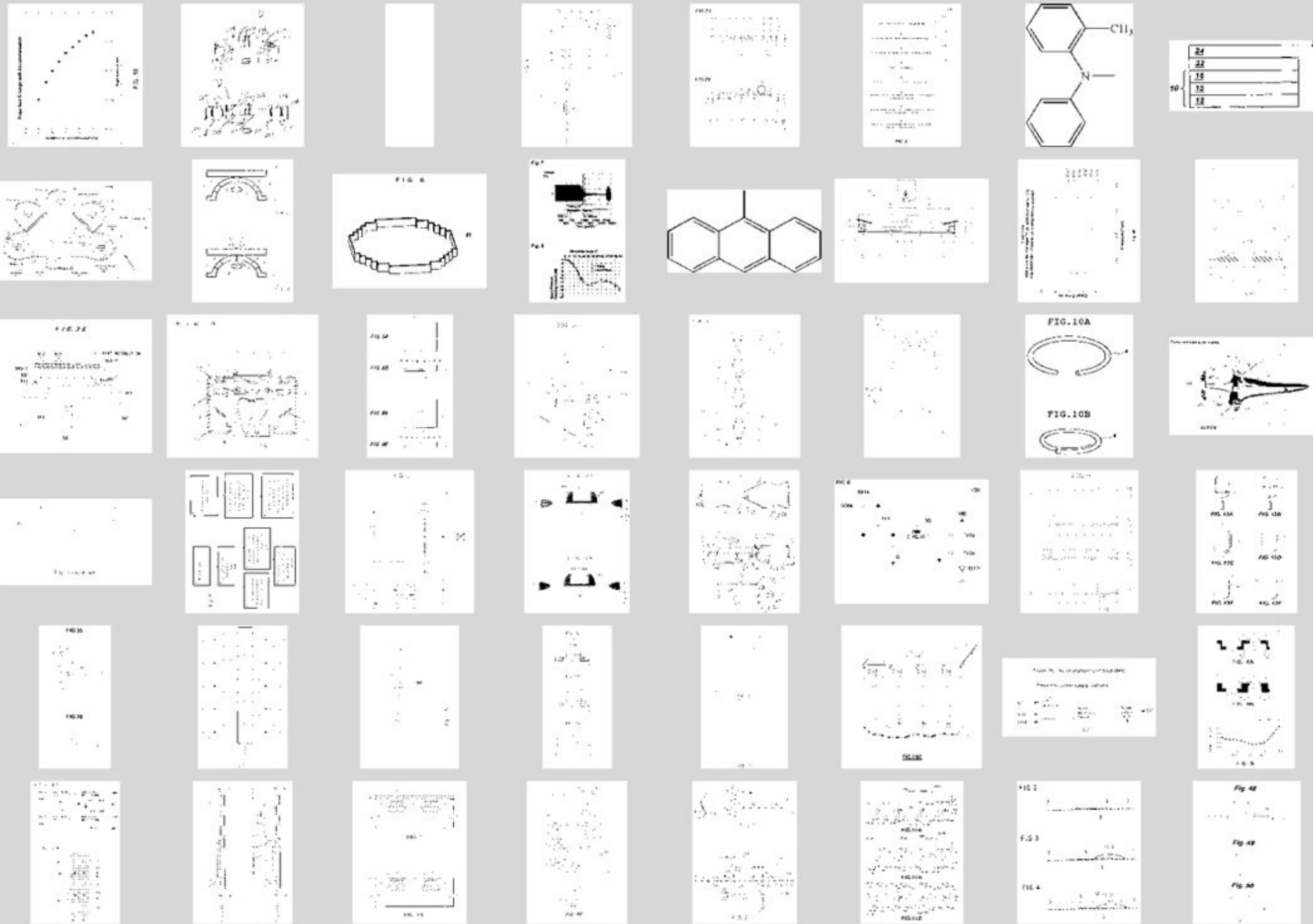


Randomly picked images (last set of 108)

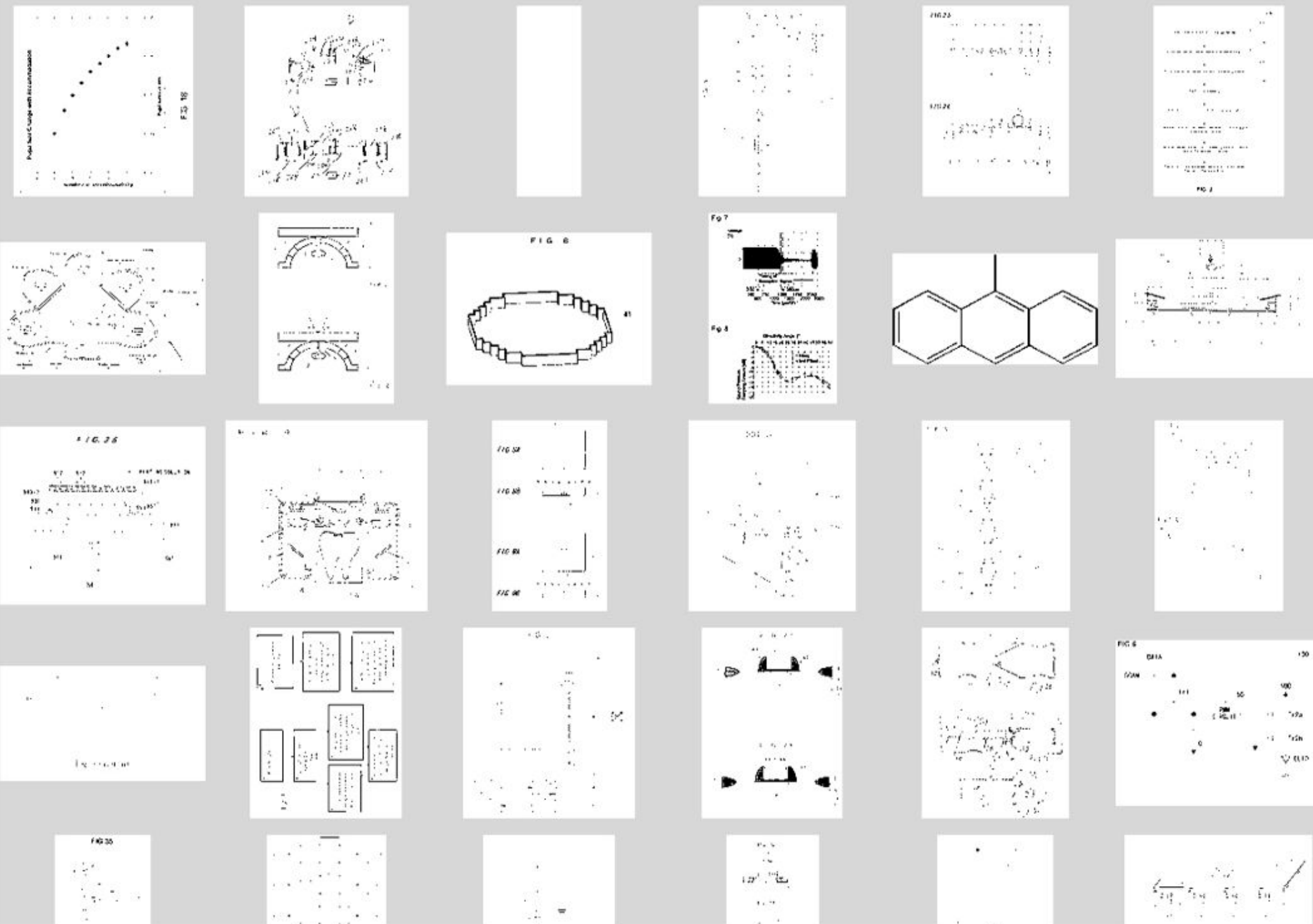
random-d-16-a



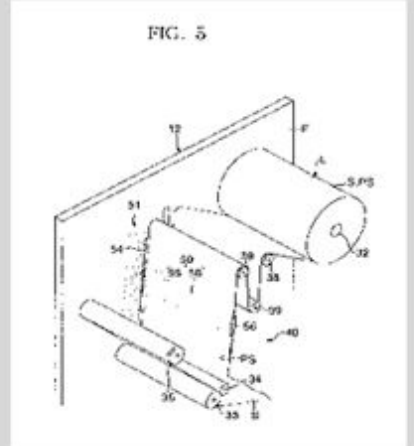
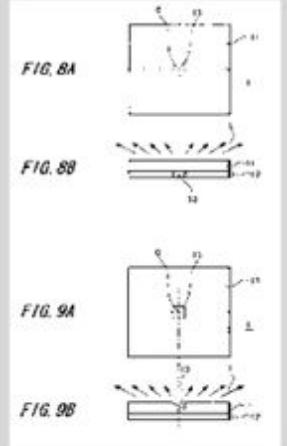
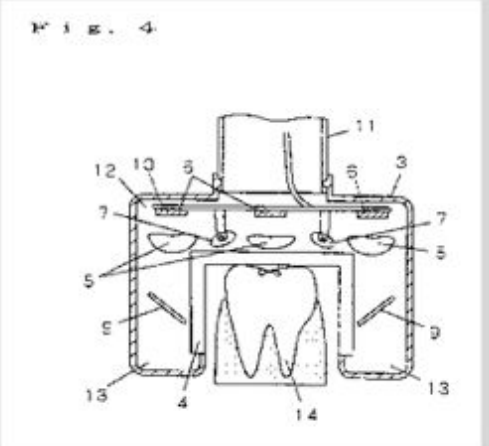
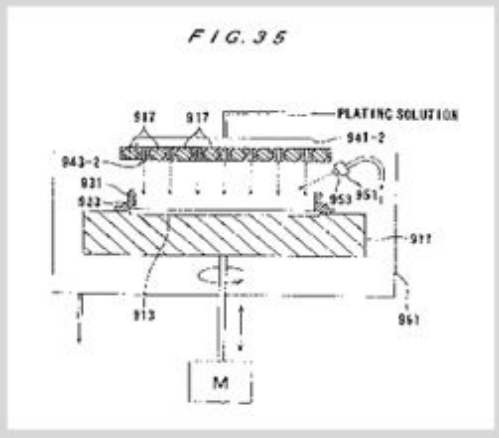
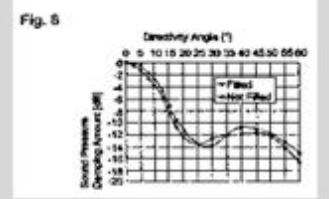
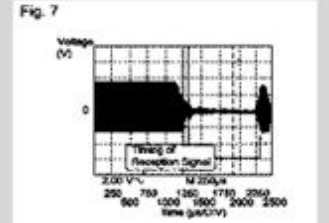
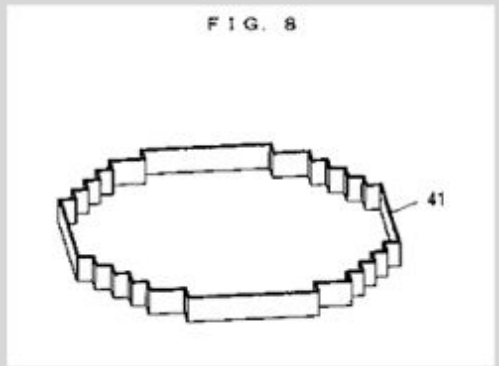
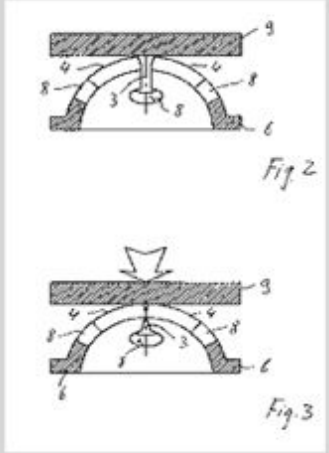
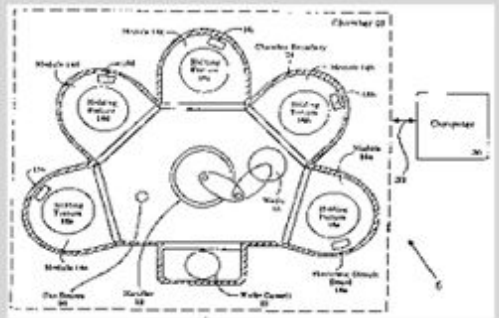
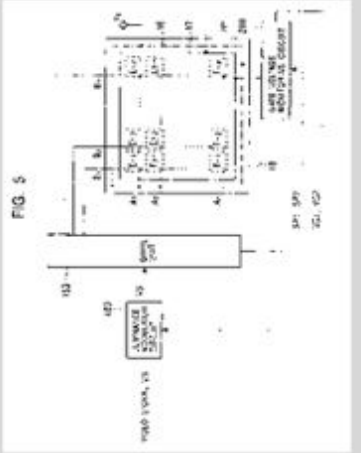
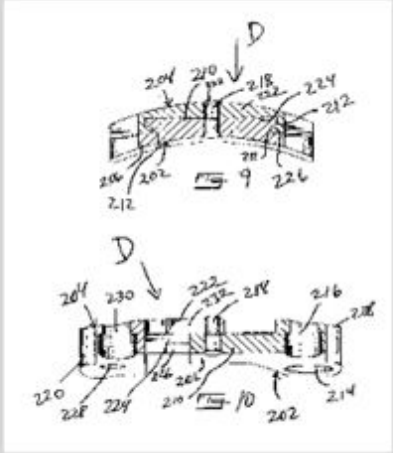
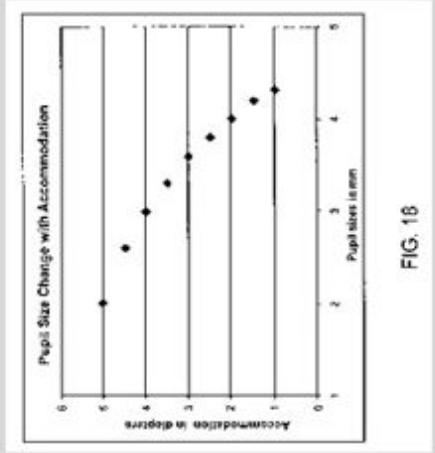
Randomly picked images (zooming in)



Randomly picked images (zooming in)



Randomly picked images (zooming in)



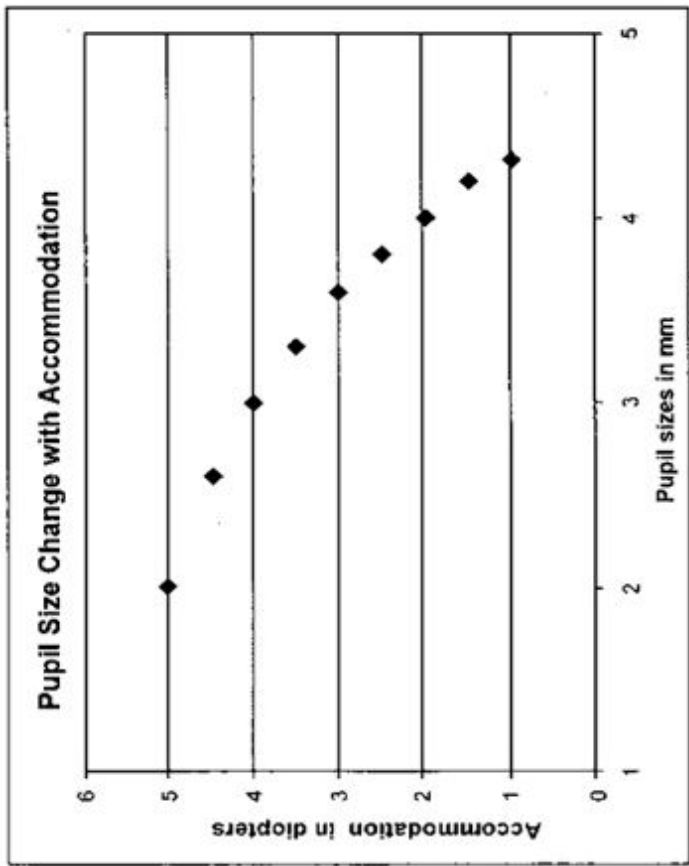


FIG. 18

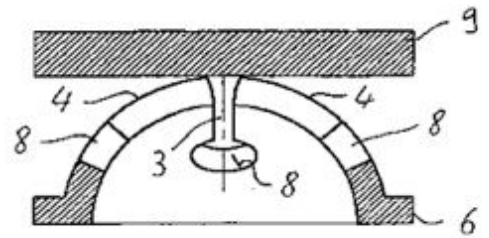
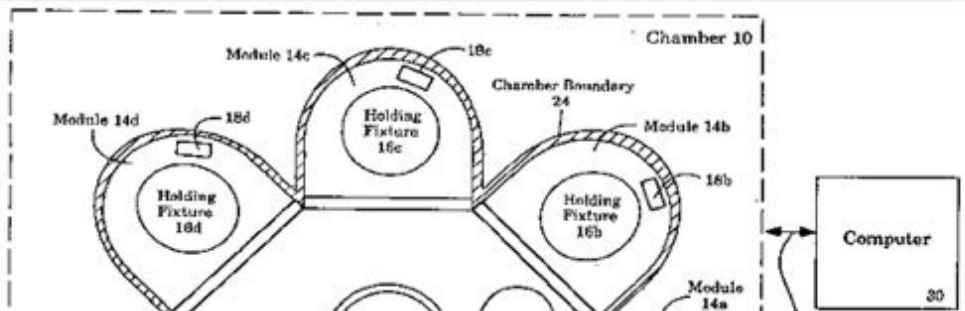
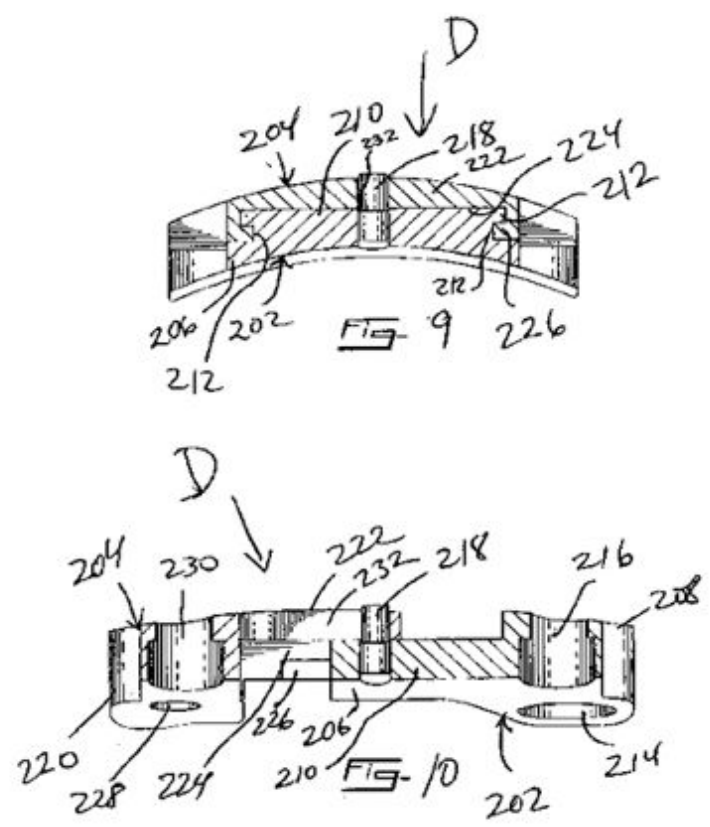


Fig. 2

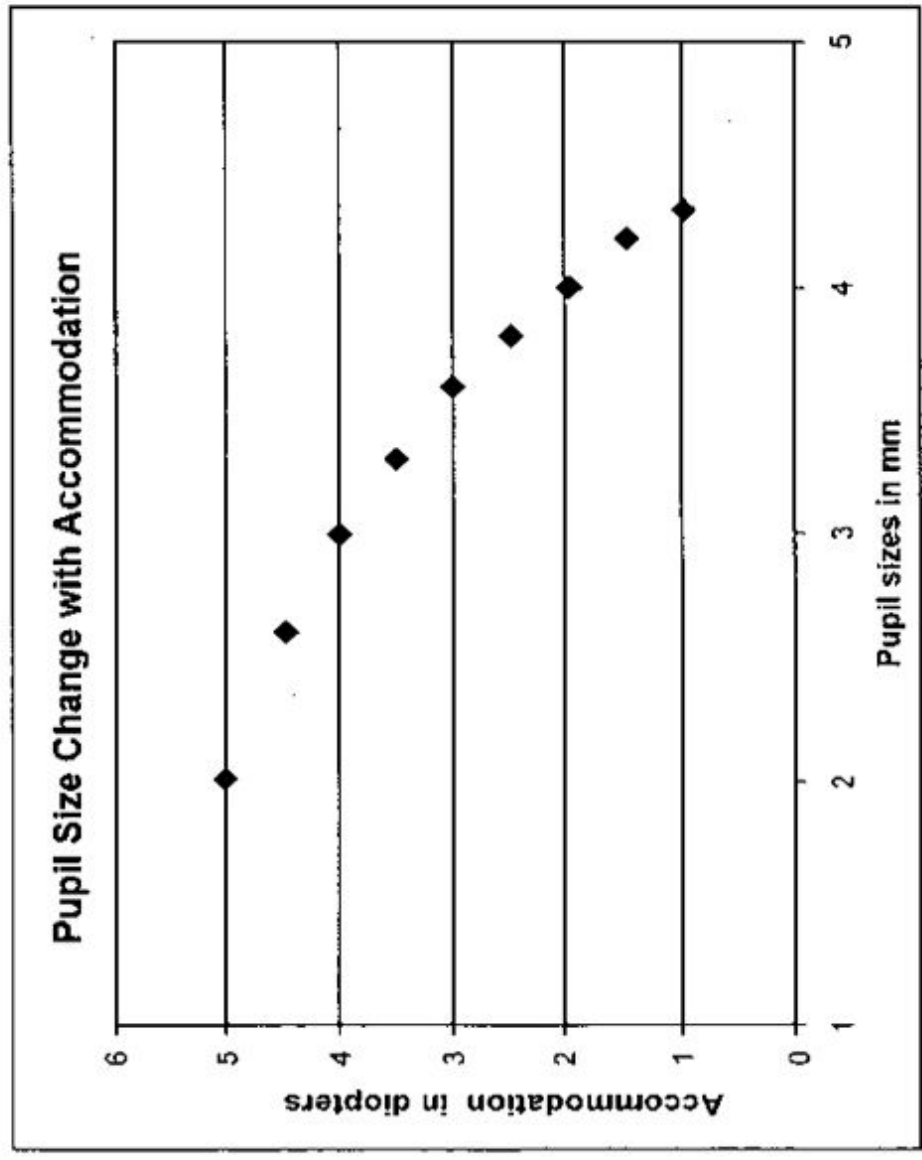
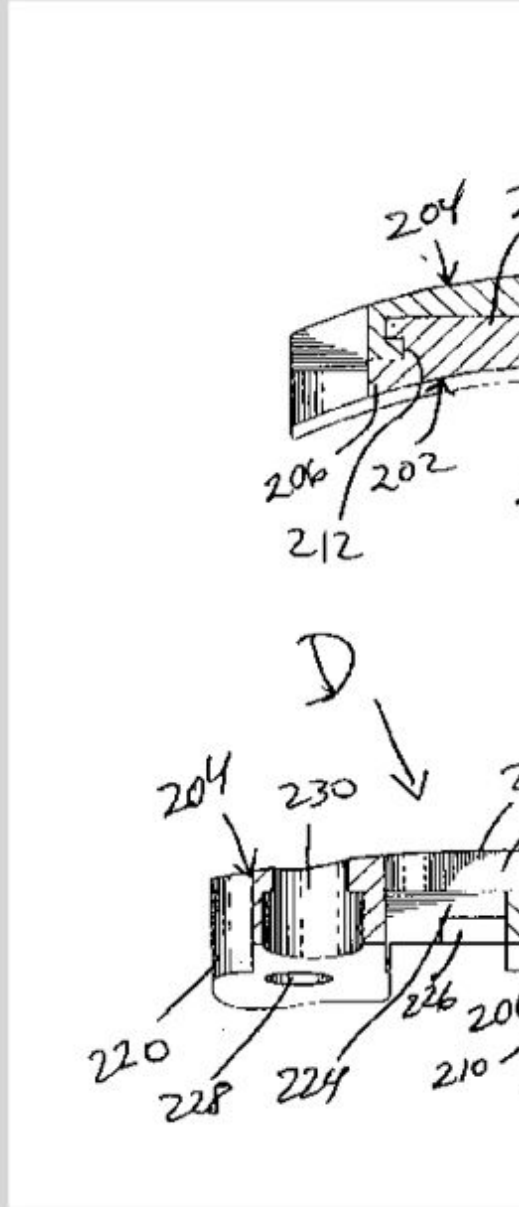


FIG. 18



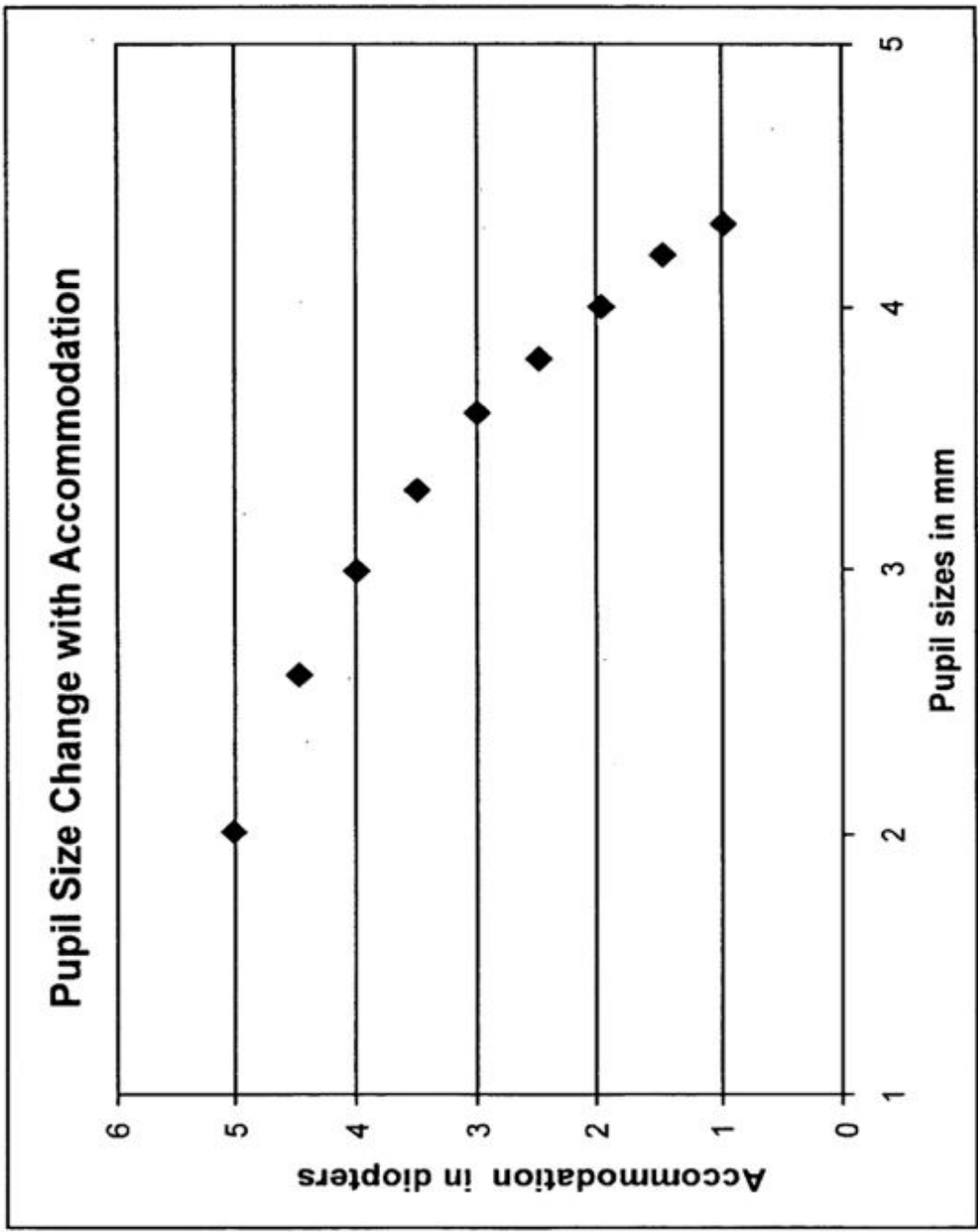


FIG. 18



What have we seen?

All black/white 1-bit bitonal

Different orientations, aspect ratio, sizes

Range of complexity (a few letters to hand-drawn sketches)

Range of different types – predominantly

- Abstract drawings

- Graphs

- Flow charts

- Gene sequences

- Program listings

- Symbols

- Chemical structures

- Tables

- Mathematics



Ideal world?

Semantically marked up entities (text & drawings obsolete)

Chemical Markup Language (CML)

Scalable Vector Graphics (SVG)

Flowchart markup language?

Tables and graphs?



Automated processing

Need dedicated features for bitonal images!
What is the analogon for SIFT-type of special features?
Predict near duplicate detection is possible (and useful!)

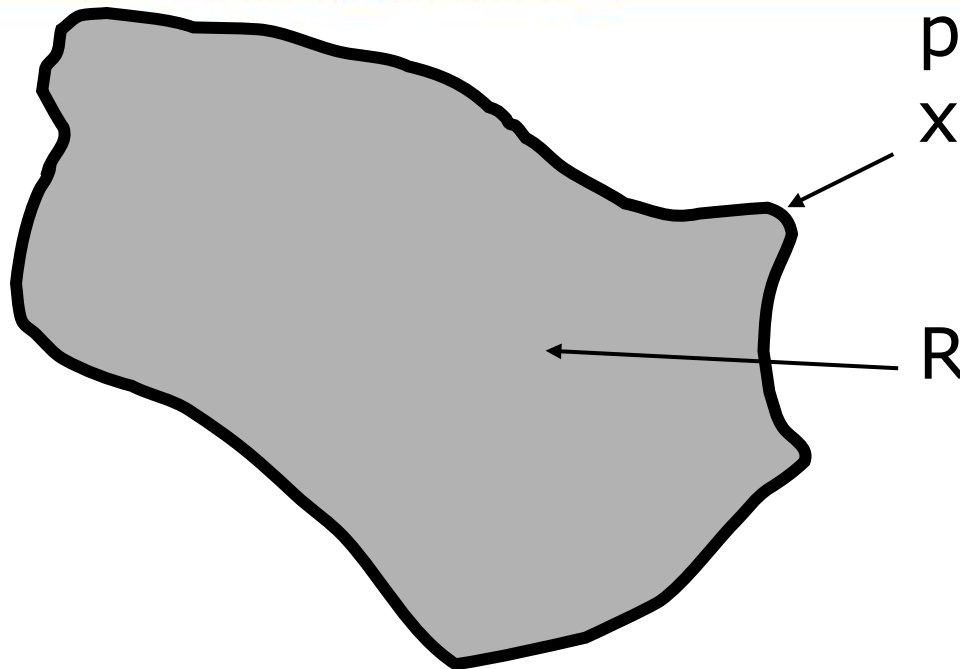
Automated extraction of structure from scans?
Word spotting



- boundary based
 - perimeter & area
 - corner points
 - circularity
 - chain codes
- region based (considering interior and holes, ...)
 - not covered here



Perimeter and area



parameterised curve
 $x(t), y(t)$

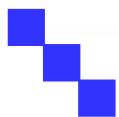
R

$$P = \int \sqrt{x'^2(t) + y'^2(t)} dt$$

~~$$A = \iint_R dx dy$$~~

~~boundary pixel count~~

count pixels in area



VS





Circularity

$$T = 4\pi \frac{A}{P^2}$$

A=area, P=perimeter

T is 1 for a circle

T is smaller than 1 for all other shapes

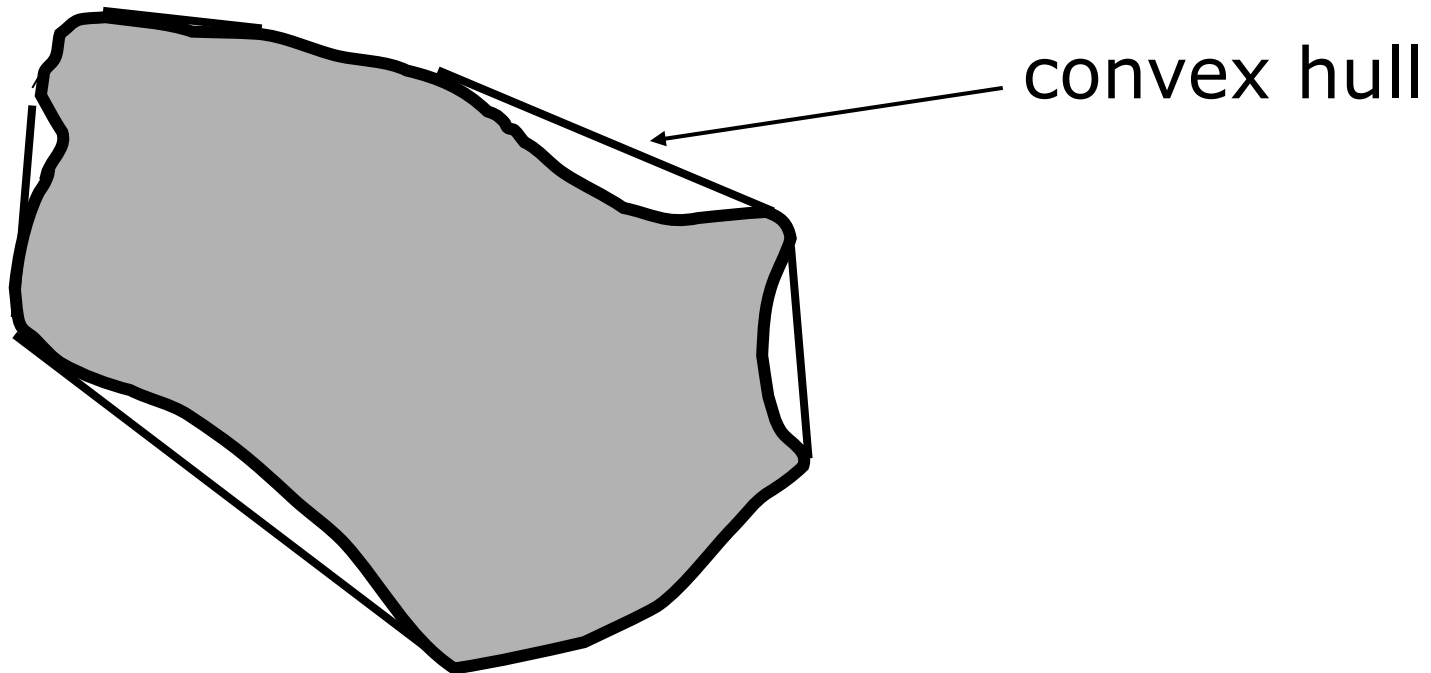
circularity is aka compactness



Convexity

ratio of perimeter of convex hull and the original curve

1 for convex shapes, less than 1 otherwise





contour description by a string of directions

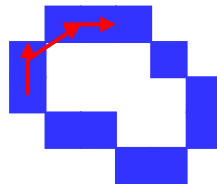
Freeman chain code

$f_1 f_2 f_3 \dots$

eight possible directions for each pixel

translation invariant, not rotation invariant

3	2	1
4	■	0
5	6	7



= 210077654343

= 100776543432

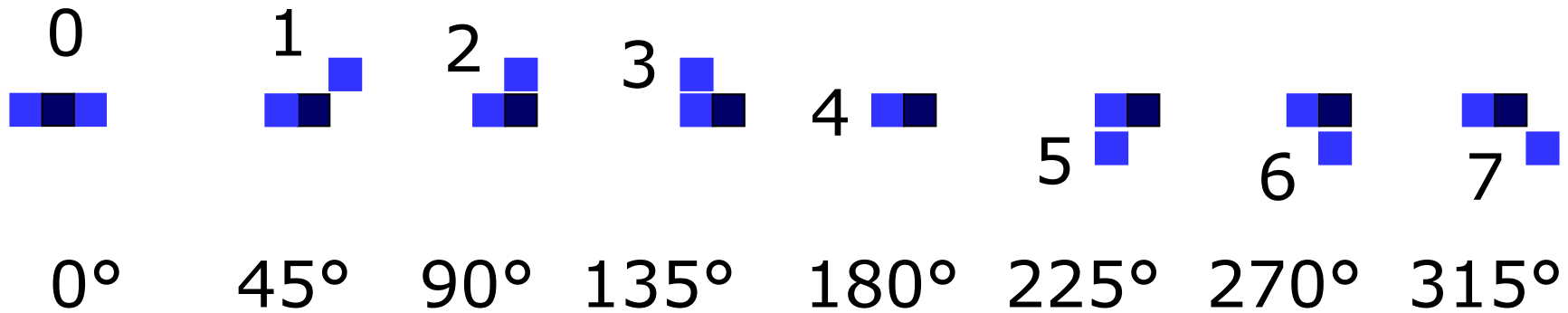
= 007765434321

choose lowest number
for closed contours

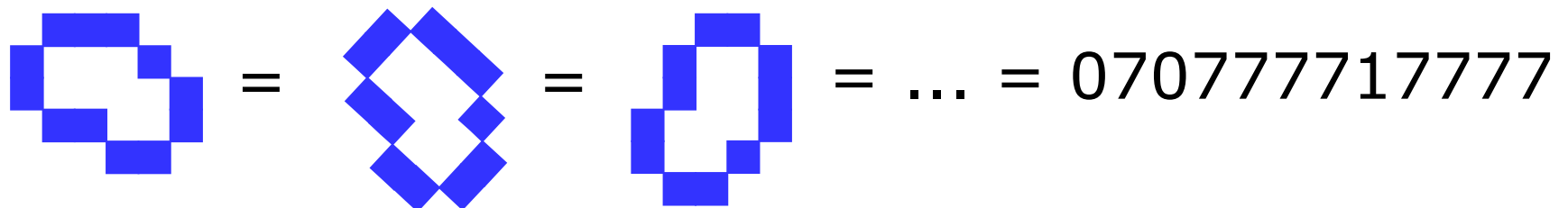


Difference chain codes

sequence of angles: $a_i = (f_{i+1} - f_i) \bmod 8$

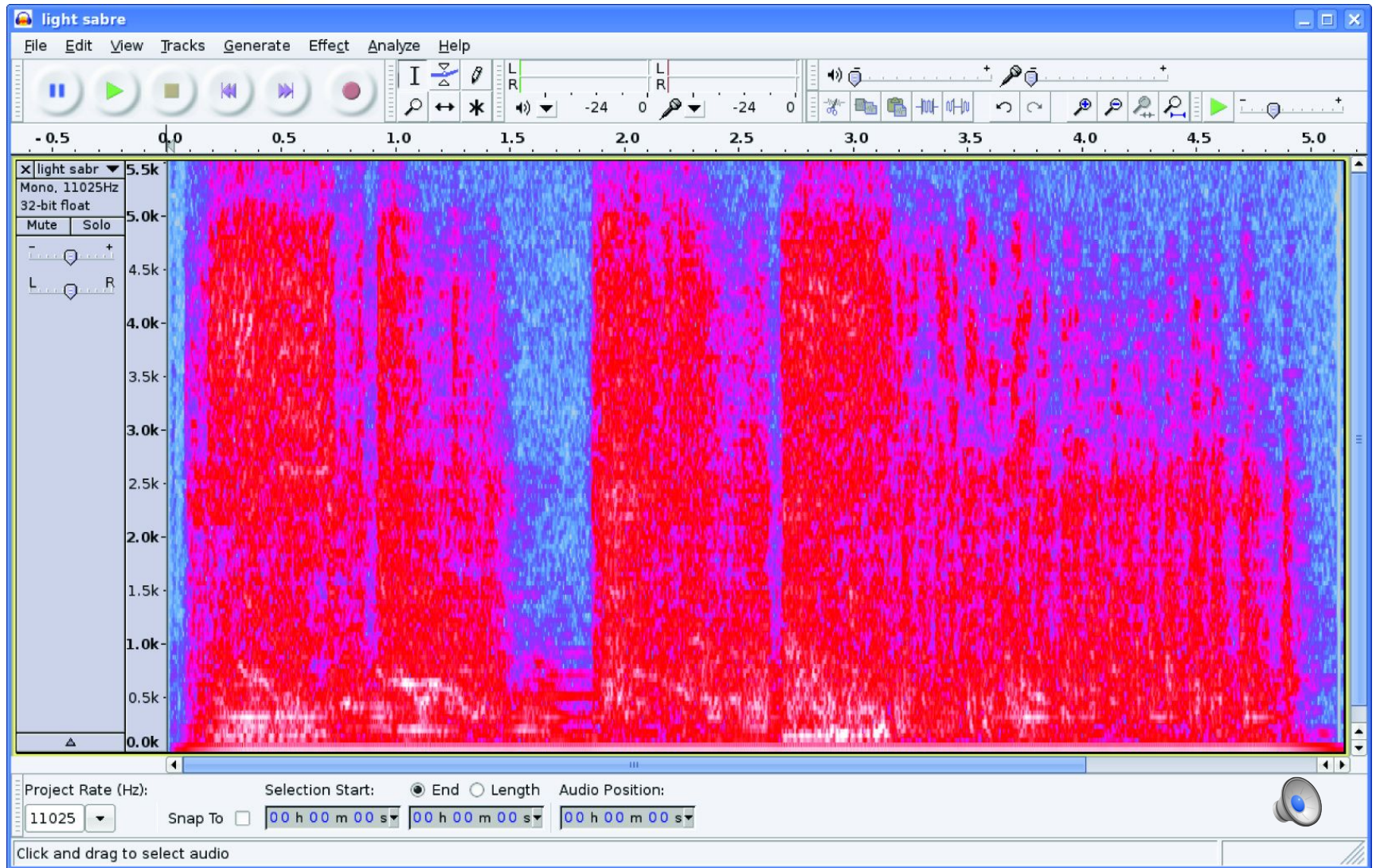


rotation invariant





Sound

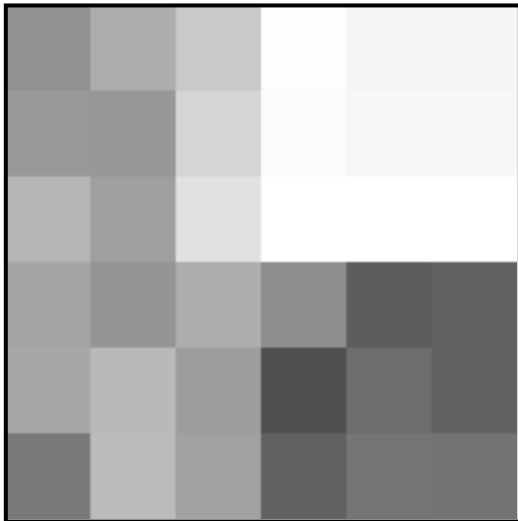




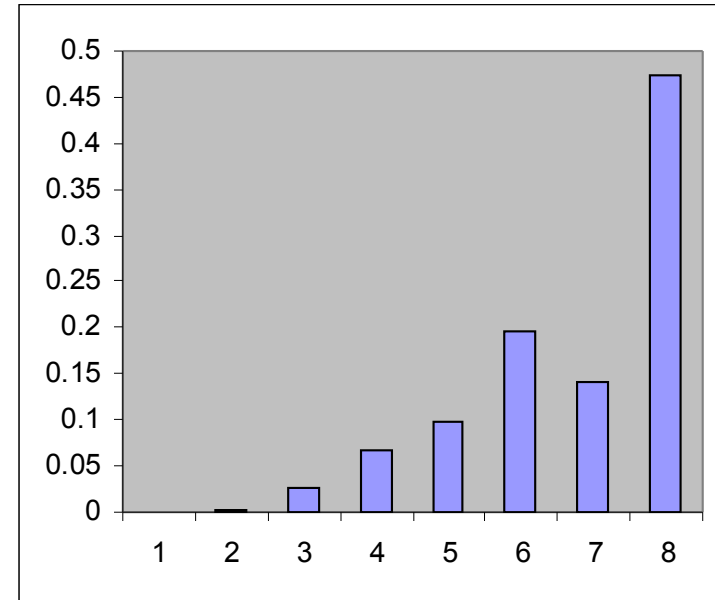
- Spectrogram
 - graph of frequencies/energy/time
- tempo, pitch, mode
- See
 - Z Liu, Y Wang and T Chen (1998). Audio feature extraction and analysis for scene segmentation and classification. *VLSI Signal Processing* 20(1-2), 69-79.



Feature vectors → histograms



145	173	201	253	245	245
153	151	213	251	247	247
181	159	225	255	255	255
165	149	173	141	93	97
167	185	157	79	109	97
121	187	161	97	117	115



1: 0	–	31	5: 128	–	159
2: 32	–	63	6: 160	–	191
3: 64	–	95	7: 192	–	223
4: 96	–	127	8: 224	–	255



Simple statistics

μ Mean

\bar{p}_2 Variance (squared standard deviation)

\bar{p}_3 3rd central moment (skewness)

$$\bar{p}_n = \frac{1}{wh} \sum_{i=1}^w \sum_{j=1}^h (p(i, j) - \mu)^n$$

where w is image width and h is image height



Moment features

$$(\mu, \sqrt{\bar{p}_2}, \text{sign}(\bar{p}_3) \sqrt[3]{|\bar{p}_3|})$$



Moment features

$$\left(\begin{array}{l} \mu_r, \sqrt{\bar{r}_2}, \text{sign}(\bar{r}_3) \sqrt[3]{|\bar{r}_3|}, \\ \mu_g, \sqrt{\bar{g}_2}, \text{sign}(\bar{g}_3) \sqrt[3]{|\bar{g}_3|}, \\ \mu_b, \sqrt{\bar{b}_2}, \text{sign}(\bar{b}_3) \sqrt[3]{|\bar{b}_3|} \end{array} \right)$$



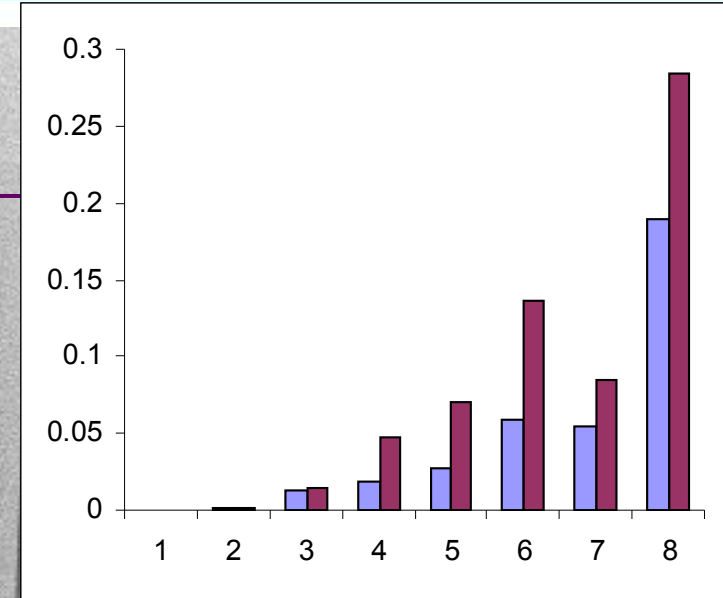
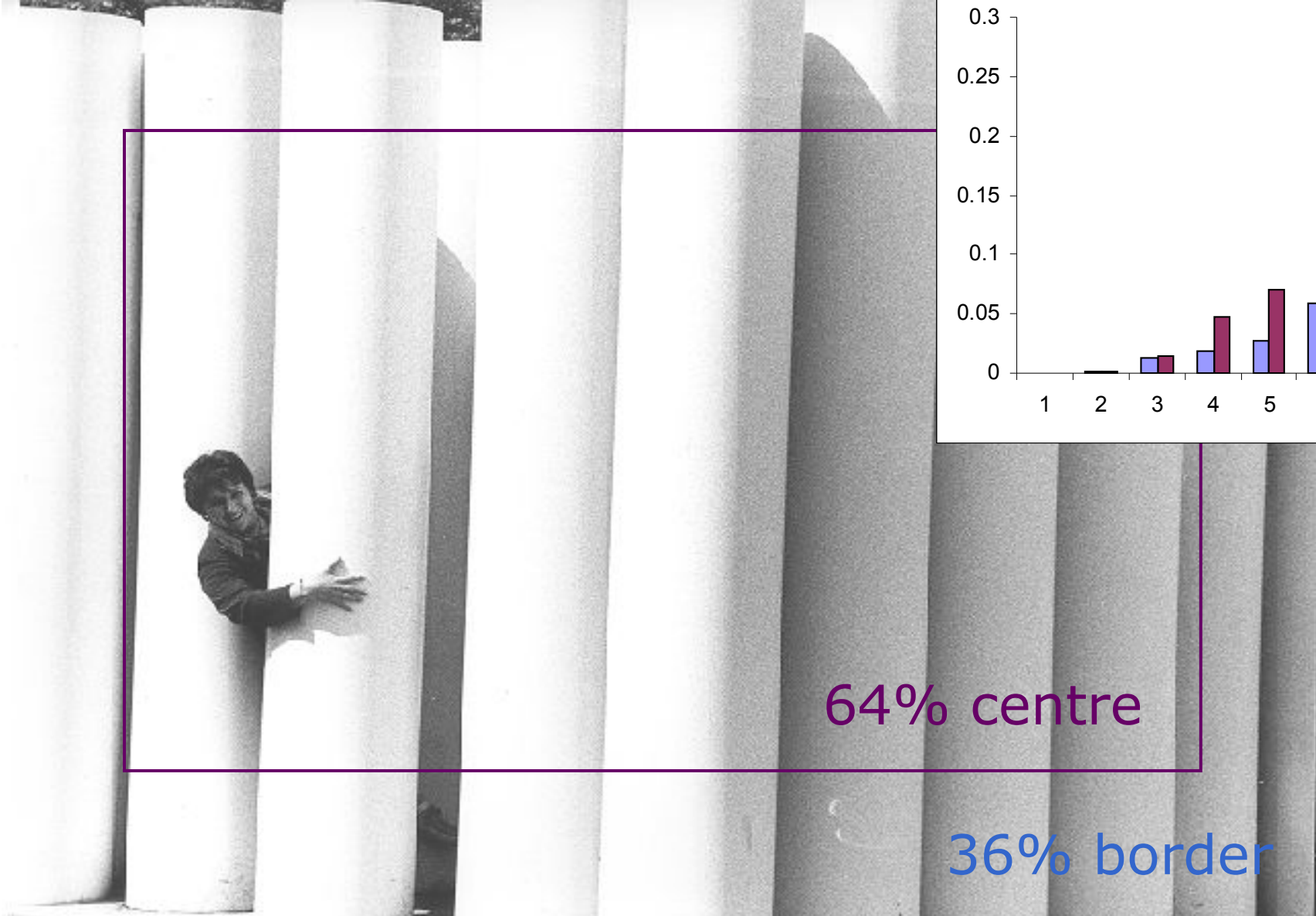
Global vs local



Global histogram also matches polar bears, marble floors, ...



Localisation

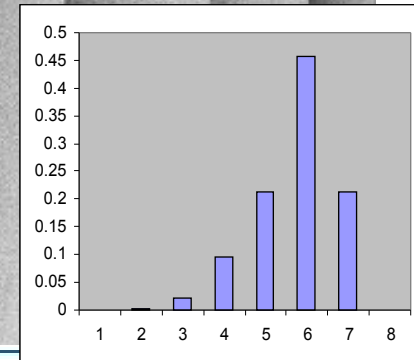
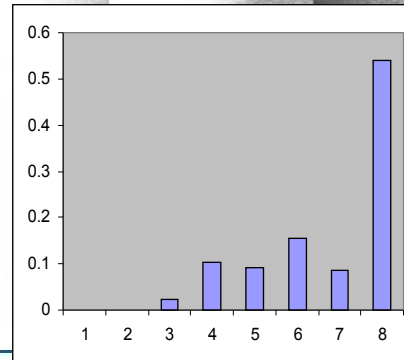
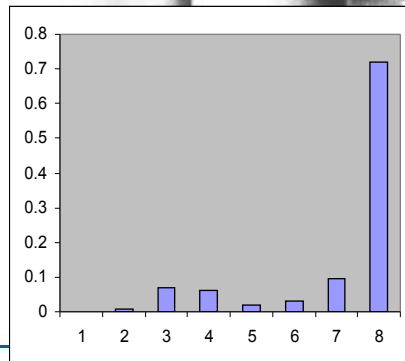
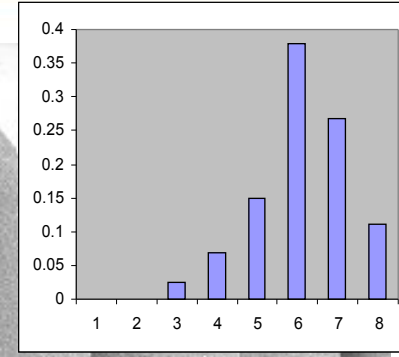
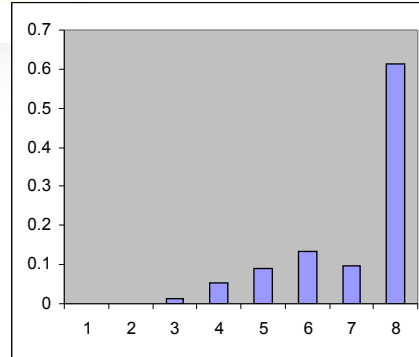
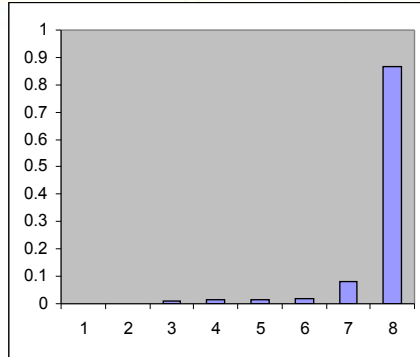


64% centre

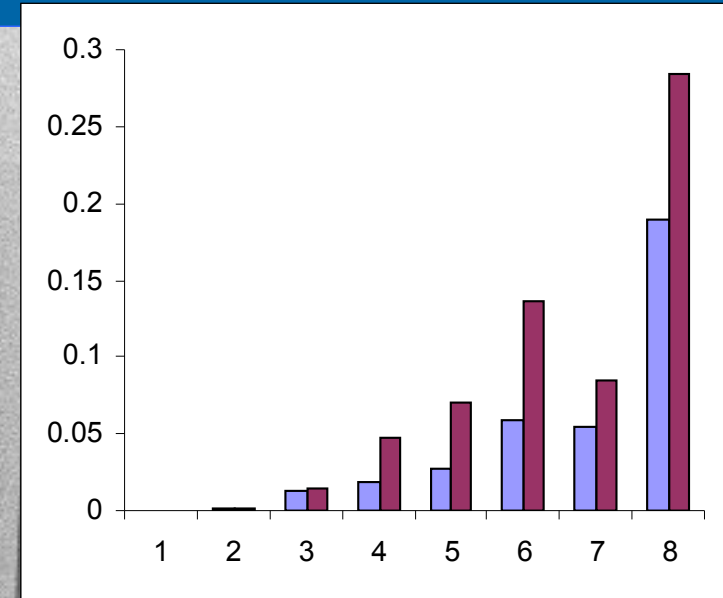
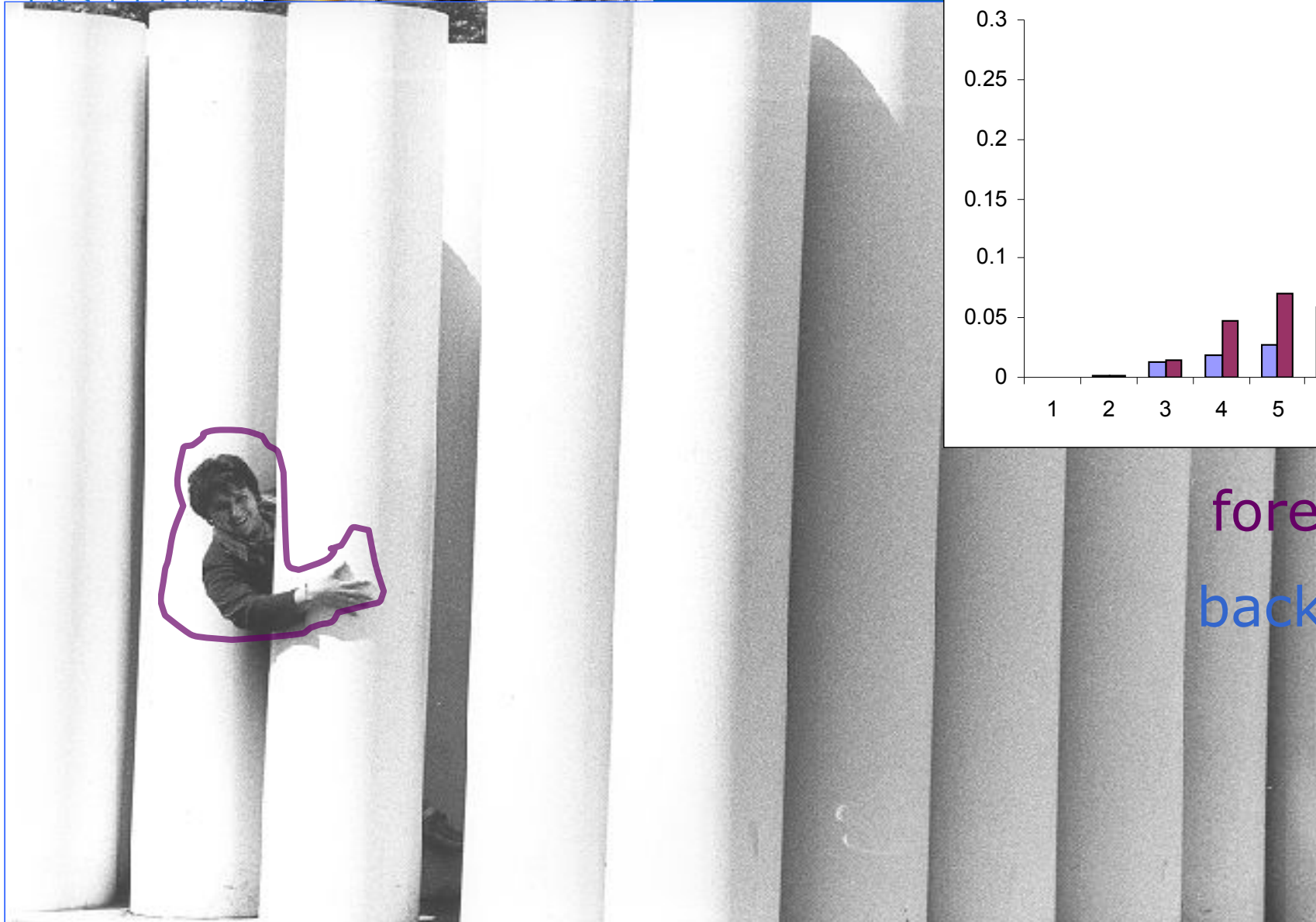
36% border



Tiled Histograms



Segmentation



foreground
background

Many PoI, ie, many feature vectors
Quantised feature vectors \approx words
Bag of word model \approx text retrieval



speed vs flexibility vs precision

Process:

1. best abstracted representation of your media
2. best method for calculating difference/similarity
3. implement efficiently, considering responsiveness and scalability



Which features are best for searching? Depends on the information need:

Looking for sunset holiday pictures in your digital shoebox?
Use colour histograms.

Want to build a wallpaper customer database? Use colour + texture.

Want to build a b/w sketch database for technical industrial designs? Use shape descriptors.

Not sure which features are best for a query (eg, if you also have abstract features such as Fourier coefficients)? Deploy **relevance feedback** and **let the system learn** the relevant features for this query...



Sketch a block diagram showing how you would implement a Multimedia Information Retrieval system for one of these scenarios:

1. Browsing wallpaper patterns in a home decorator store
2. Finding “interesting” photos in a personal collection of holiday snaps
3. Managing industrial design pattern templates for a manufacturing company

Think about:

what types of features you might use
what would the query be
the user interface